

CS423 Finite Automata & Theory of Computation

TTh 12:30 - 13:50 in Small Physics Lab 111 (section 1) TTh
9:30 - 10:50 in Blow 331 (section 2)

Prof. Weizhen Mao, wxmaox@wm.edu, wm@cs.wm.edu

General Information

- ▶ Office Hours: TTh 11:00 - 12:00 in 114 McGI and W 2:30 - 3:00 on zoom or by email
- ▶ Grader: TBD for section 1 (office hour TBD on BB)
- ▶ Grader: TBD for section 2 (office hour TBD on BB)
- ▶ Textbook: Intro to the theory of computation (any edition), Michael Sipser. An e-book in PDF maybe available online.
- ▶ Prerequisites/background: Linear algebra, Data structures and algorithms, and Discrete math

Complexity Theory:

- ▶ Computability Theory is the study of what can or cannot be computed by a TM/algorithm, among all problems.
- ▶ Complexity Theory is the study of what can or cannot be computed **efficiently** by a TM/algorithm, among all decidable/solvable problems.
- ▶ For the set of all solvable problems, it is further classified into various **complexity classes** based on the efficiency of algorithms solving these problems.
- ▶ Complexity Theory is the study of the definition and properties of these classes.

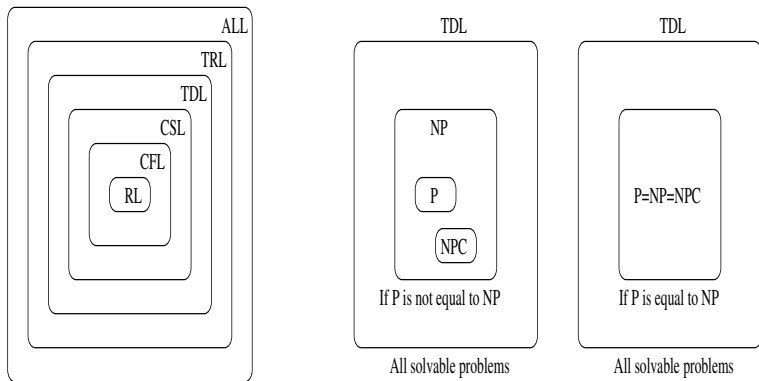


Figure 1: Three complexity classes if $P=NP$ or $P \neq NP$

11.1 The class of \mathbf{P} (Sipser 7.2)

- ▶ Definition: \mathbf{P} is the class of problems solvable in polynomial time (number of steps) by deterministic TMs. Polynomial $O(n^c)$, where n is input size and c is a constant. Problems in \mathbf{P} are "tractable" (not so hard).
- ▶ Why use polynomial as the criterion?
 - ▶ If a problem is not in \mathbf{P} , it often requires unreasonably long time to solve for large-size inputs.
 - ▶ \mathbf{P} is independent of all models of computation, except nondeterministic TM.
- ▶ Problems in \mathbf{P} : Sorting, Searching, Selecting, Minimum Spanning Tree, Shortest Path, Matrix Multiplication, etc.
- ▶ Review of asymptotic notation: O , Ω , Θ
- ▶ Examples of polynomial and polylog functions: $O(1)$, $O(n)$, $O(n^2)$, $O(n^d)$, $O(\log n)$, $O((\log n)^c)$, $O(n^3 \log n)$, $O(n^c(\log n)^d)$

11.2 The class of NP (Sipser 7.3)

- ▶ An NTM is an unrealistic (unreasonable) model of computing which can be simulated by other models with an exponential loss of efficiency.
It is a useful concept that has had great impact on the theory of computation.
- ▶ NTM $N = (Q, \Sigma, \Gamma, \delta, q_0, q_{accept}, q_{reject})$, where $\delta : Q \times \Gamma \rightarrow 2^P$ for $P = Q \times \Gamma \times \{L, R\}$.
- ▶ $\delta(q, X)$ is a set a moves. Which one to choose? This is nondeterminism. The computation can be illustrated by a tree, with each node representing a configuration.

- ▶ Nondeterminism can be viewed as a kind of parallel computation wherein multiple independent processes or threads can be running concurrently.
When a nondeterministic machine splits into several choices, that corresponds to a process forking into several children, each then proceeding separately. If at least one process accepts, then the entire computation accepts.
- ▶ Time complexity of nondeterministic TMs (NTMs): Let N be an NTM that is a decider (where all computation paths halt in the tree for any input). The time complexity of N , $f(n)$, is the maximum number of steps that N uses on any computation path for any input of length n . In other words, $f(n)$ is the maximum height of all computation trees for all input of length n .

- ▶ An unreasonable model of computation:

Theorem; Every $T(n)$ -time multi-tape TM has an equivalent $O(T^2(n))$ -time single-tape TM.

Theorem: Every $T(n)$ -time single-tape NTM has an equivalent $O(2^{O(T(n))})$ -time single-tape DTM.

- ▶ Definition: **NP** is the class of problems solvable in polynomial time by nondeterministic TMs.
- ▶ Another definition of nondeterministic TMs (algorithms):
 - ▶ Guessing phase: Guess a solution (always on target).
 - ▶ Verifying phase: Verify the solution.

Example: TSP (DEC) is in **NP**.

INSTANCE: An edge-weighted graph $G(V, E, w)$ and a bound $B \geq 0$.

QUESTION: Is there a tour (a cycle that passes through each node exactly once) in G with total weight no more than B ?
Define the following NTM N to solve TSP in polynomial time.

NTM N = "On input $\langle G, B \rangle$

1. Nondeterministically **guess** a tour T $O(|V|)$
2. **Verify** if T includes every node once $O(|V|)$
3. Compute $sum \leftarrow \sum_{e \in T} w(e)$ $O(|V|)$
4. **Verify** if $sum \leq B$. If true, answer **yes**; else **No** $O(1)$

Note 1: The time complexity of N is $O(|V|)$.

Note 2: If the answer to the QUESTION is "Yes", N guarantees that the right T will be guessed in step 1.

Note 3: The acceptance of an input by a nondeterministic machine is determined by whether there is an accepting computation among all, possibly exponentially many, computations.

In the above proof, if there is a solution, i.e., a tour with total weight no more than B , it will always be generated by the Turing machine. This is like that a nondeterministic machine has a guessing power.

A tour can only be found by a deterministic machine in exponential time, however, it can be found by a nondeterministic machine in just linear steps. Any nondeterministic proof should always contain two stages: Guessing and verifying.

What needs to be guessed? What needs to be verified? What is the time complexity?

Example: Graph Coloring (GC) is in **NP**.

INSTANCE: Graph $G = (V, E)$, and $B \geq 0$

QUESTION: Is there a coloring scheme of the nodes that uses no more than B colors such that no two nodes connected by an edge are given the same color?

NTM $N =$ "On input $\langle G, B \rangle$

1. Guess a coloring scheme (in polynomial time) $c : V \rightarrow C$
2. Verify if (1) $|C| \leq B$ and (2) $\forall (u, v) \in E, c(u) \neq c(v)$
3. if true, answer **yes**; else answer **no**

So we have a **nondeterministic** algorithm (or TM) that **guesses** a coloring scheme (or function) and **verifies** that (1) for any $(u, v) \in E, c(u) \neq c(v)$ and that (2) the number of colors used is no more than B , and further, all these can be done in **polynomial time** of $O(|V|) + O(|E|)$. So GC is in **NP**.

- ▶ Theorem: $\mathbf{P} \subseteq \mathbf{NP}$. (Two possibilities: $\mathbf{P} \subset \mathbf{NP}$ or $\mathbf{P} = \mathbf{NP}$)
Any deterministic TM is a special case of nondeterministic TMs.
- ▶ Theorem: Any $\Pi \in \mathbf{NP}$ can be solved by a deterministic TM in time $O(c^{p(n)})$ for some $c > 0$ and polynomial $p(n)$.
- ▶ Open problem: $\mathbf{P} = \mathbf{NP}$?
The west wall bricks on the CS building at Princeton, 1989:
x1010000x
x0111101x
x1001110x
x1010000x
x0111111x

- ▶ Definition of **Polynomial Reduction** \leq_p (cf. \leq_m and \leq)
 Let Π_1 and Π_2 be two decision problems, and $\{I_1\}$ and $\{I_2\}$ be sets of instances for Π_1 and Π_2 , respectively.
 We say there is a polynomial reduction from Π_1 to Π_2 , or $\Pi_1 \leq_p \Pi_2$, if there is $f : \{I_1\} \rightarrow \{I_2\}$ such that
 - (1) f can be computed in polynomial time and
 - (2) I_1 has a “yes” solution if and only if $f(I_1)$ has a “yes” solution.
- ▶ Theorem: If $\Pi_1 \leq_p \Pi_2$, then $\Pi_2 \in \mathbf{P}$ implies $\Pi_1 \in \mathbf{P}$.
- ▶ Theorem: If $\Pi_1 \leq_p \Pi_2$ and $\Pi_2 \leq_p \Pi_3$, then $\Pi_1 \leq_p \Pi_3$.
- ▶ *Remark:* \leq_p means “no harder than”.

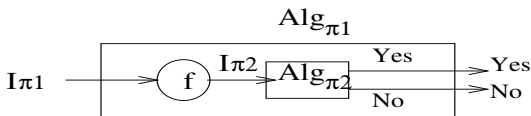


Figure 2: Polynomial reduction $\Pi_1 \leq_p \Pi_2$

11.4 The class of NPC (*Sipser 7.4*)

- ▶ Definition 1: **NPC** (**NP**-complete) is the class of the hardest problems in **NP**
- ▶ Definition 2: $\Pi \in \mathbf{NPC}$ if $\Pi \in \mathbf{NP}$ and $\forall \Pi' \in \mathbf{NP}, \Pi' \leq_p \Pi$.
- ▶ Definition 3: $\Pi \in \mathbf{NPC}$ if $\Pi \in \mathbf{NP}$ and $\exists \Pi' \in \mathbf{NPC}$ such that $\Pi' \leq_p \Pi$
- ▶ Theorem: If $\exists \Pi \in \mathbf{NPC}$ such that $\Pi \in \mathbf{P}$, then $\mathbf{P} = \mathbf{NP}$.
- ▶ Theorem: If $\exists \Pi \in \mathbf{NPC}$ such that $\Pi \notin \mathbf{P}$, then $\mathbf{P} \neq \mathbf{NP}$.

Some most important classes: Definitions and proofs

- ▶ **P**: class of problems solvable in polynomial-time by DTM.
To prove $\Pi \in \mathbf{P}$, design a polynomial-time algorithm.
- ▶ **NP**: class of problems solvable in polynomial-time by NTM.
To prove $\Pi \in \mathbf{NP}$, design a polynomial-time nondeterministic algorithm of two steps: guess and verify.
- ▶ **NPC**: class of all hardest problems in **NP**.
To prove $\Pi \in \mathbf{NPC}$, prove (1) $\Pi \in \mathbf{NP}$ and (2) $\exists \Pi' \in \mathbf{NPC}$ s.t. $\Pi' \leq_p \Pi$
- ▶ **NP-hard**: A problem X is NP-hard, if there is an NP-complete problem Y , such that Y is reducible to X in polynomial time. (Note X does not need to be in **NP**)

Possible relations among P, NP, NP-complete, NP-hard:

$\mathbf{P} \subset \mathbf{NP}$, $\mathbf{NP} \cap \mathbf{NP-hard} = \mathbf{NP-complete}$, $\mathbf{P} \cup \mathbf{NP-complete} = \emptyset$

Satisfiability (SAT):

INSTANCE: A boolean formula ϕ in CNF with variables x_1, \dots, x_n and clauses c_1, \dots, c_m

QUESTION: Is ϕ satisfiable? (Is there a truth assignment A to x_1, \dots, x_n such that ϕ is true?)

$$L_{SAT} = \{ \langle \phi \rangle \mid \exists A \text{ that satisfies } \phi \}$$

Example of an instance for SAT:

- ▶ Variables: x_1, x_2, x_3, x_4
- ▶ Literals: Any variables and their negations, such as x_1, \bar{x}_3
- ▶ Clauses: $c_1 = x_1 \vee \bar{x}_2 \vee x_3$, $c_2 = x_1 \vee x_2$, $c_3 = \bar{x}_1 \vee x_2 \vee \bar{x}_3 \vee x_4$
- ▶ Function/formula: $\phi = c_1 \wedge c_2 \wedge c_3$
- ▶ The instance ϕ is T by assignment $x_1 = T, x_2 = x_3 = x_4 = F$.
Note: Many assignments satisfy ϕ , but we only need one.

Cook's Theorem: $SAT \in \mathbf{NPC}$. (Need to prove (1) $SAT \in \mathbf{NP}$ and (2) $\forall \Pi \in \mathbf{NP}, \Pi \leq_p SAT$.)

First Step: How to prove SAT is in **NP**?

NTM $N =$ "On input $\langle \phi \rangle$ in CNF

1. Guess a truth assignment A $O(n)$
2. Verify if $\phi = T$ under A $O(n+m)$
3. If T , **accept**; else **reject**"

SAT is solvable by a NTM in polynomial time, thus in **NP**.

Second step: How to prove $\forall \Pi \in \mathbf{NP}, \Pi \leq_p SAT$, or equivalently, for any polynomial-time NTM M , $L(M) \leq_p L_{SAT}$?

Will not discuss this proof. But if interested, go to the final few pages of this slide set for details.

11.5 NP-complete problems (Sipser 7.5, pp.310-322)

How to prove Π_2 is **NP**-complete:

- ▶ Show that $\Pi_2 \in \mathbf{NP}$.
- ▶ Choose a known **NP**-complete Π_1 .
- ▶ Construct a reduction f from Π_1 to Π_2 .
- ▶ Prove that f is a polynomial reduction by showing (1) f can be computed in polynomial time and (2) $\forall I_1$ for Π_1 , I_1 is a yes-instance for Π_1 if and only if $f(I_1)$ is a yes-instance for Π_2 .

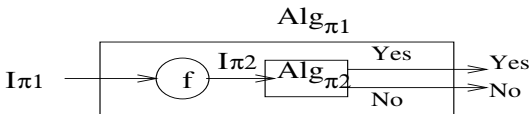


Figure 3: Polynomial reduction $\Pi_1 \leq_p \Pi_2$

Seven basic **NP**-complete problems.

- ▶ 3-Satisfiability (3SAT): (Reduced from SAT)
INSTANCE: A formula α in CNF with each clause having three literals.
QUESTION: Is α satisfiable?
- ▶ 3-Dimensional Matching (3DM): (Reduced from 3SAT)
INSTANCE: $M \subseteq X \times Y \times Z$, where X, Y, Z are disjoint and of the same size.
QUESTION: Does M contain a matching, which is $M' \subseteq M$ with $|M'| = |X|$ such that no two triples in M' agree in any coordinate?
- ▶ PARTITION: (Reduced from 3DM)
INSTANCE: A finite set A of numbers.
QUESTION: Is there $A' \subseteq A$ such that $\sum_{a \in A'} a = \sum_{a \in A - A'} a$?

- ▶ Vertex Cover (VC): (Reduced from 3SAT)
INSTANCE: A graph $G = (V, E)$ and $0 \leq k \leq |V|$.
QUESTION: Is there a vertex cover of size $\leq k$, where a vertex cover is $V' \subseteq V$ such that $\forall (u, v) \in E$, either $u \in V'$ or $v \in V'$?
- ▶ Hamiltonian Circuit (HC): (Reduced from VC)
INSTANCE: A graph $G = (V, E)$.
QUESTION: Does G have a Hamiltonian circuit, i.e., a tour that passes through each vertex exactly once?
- ▶ CLIQUE: (Reduced from VC)
INSTANCE: A graph $G = (V, E)$ and $0 \leq k \leq |V|$.
QUESTION: Does G contain a clique (complete subgraph) of size $\geq k$?

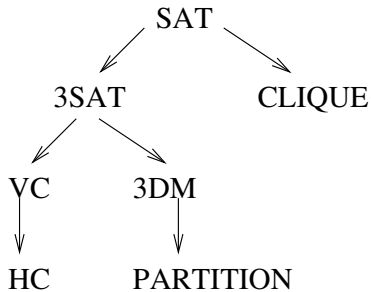


Figure 4: Seven basic NP-complete problems

Example to prove reduction: KNAPSACK Problem

INSTANCE: $U = \{u_1, \dots, u_n\}$, W (max weight knapsack holds), functions $w : U \rightarrow \mathbb{R}^+$ and $v : U \rightarrow \mathbb{R}^+$, bound $B \geq 0$.

QUESTION: Is there $U' \subseteq U$ s.t. $\sum_{u_i \in U'} w(u_i) \leq W$, and $\sum_{u_i \in U'} v(u_i) \geq B$?

Show $\text{PARTITION}_{\leq p} \leq_p \text{KNAPSACK}$.

For any instance $\{a_1, \dots, a_n\}$ in PARTITION, define the following instance for KNAPSACK:

- ▶ $U = \{u_1, \dots, u_n\}$
- ▶ $w(u_i) = a_i$ and $v(u_i) = a_i$, for all i
- ▶ $W = B = \frac{1}{2} \sum_{i=1}^n a_i$

Show that (1) the above construction can be done in polynomial time and (2) there is a partition $A' \subseteq A$ iff there is a subset U' s.t. $\sum_{u_i \in U'} w(u_i) \leq \frac{1}{2} \sum_{i=1}^n a_i$ and $\sum_{u_i \in U'} v(u_i) \geq \frac{1}{2} \sum_{i=1}^n a_i$.

Example to prove reduction: Hitting Set (HS) problem

INSTANCE: Set S , collection C of subsets of S , $K \geq 0$

QUESTION: Does S contain a HS S' of size $\leq K$? (S' is a HS if S' has at least one element from each subset in C .) $VC \leq_p HS$.

Instance for VC: $G = (V, E)$ and $B \geq 0$

Instance for HS: $S = V$, $C = \{\{u, v\} \mid \forall e = (u, v) \in E\}$, $K = B$

Goal: G has a VC of size $\leq B$ iff S has a HS of size $\leq K$.

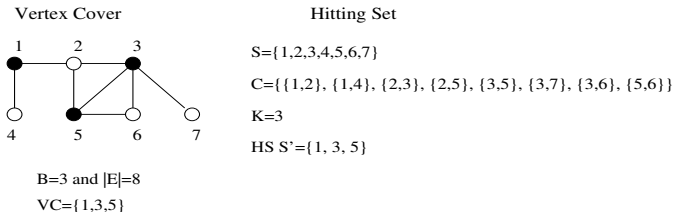


Figure 5: An example of reduction from VC to HS

Review of Automata Theory

- ▶ RL, CFL, DFA, NFA, PDA, Regular expressions
- ▶ Closure properties for the above sets of languages
- ▶ Pumping Lemmas for RL
- ▶ Chomsky Language Hierarchy
- ▶ Prove by contradiction

Review of Computability Theory

- ▶ TDL: How to prove a language is TDL
- ▶ Closure properties of TDLs: union, intersection, concatenation, star, complement
- ▶ A TM that decides (accept, reject)
- ▶ TRL: How to prove a language is TRL
- ▶ The closure properties of TRLs: union, intersection, concatenation, star, homomorphism
- ▶ TM to decide/accepts/recognizes. NTM to guess/verify
- ▶ TD, non-TD, TR, non-TR (How to prove)
- ▶ Closure properties for the above sets of languages
- ▶ A language and its complement: Three scenarios (both TD, one TR but non-TD other non-TR, both non-TR)
- ▶ Important languages: A_D , A_{TM} , $HALT_{TM}$, etc.

- ▶ Reduction $A \leq B$ is to show any TM that decides B can be used to define a TM that decides A . (A is no harder than B or B is at least as hard as A .)
- ▶ P, NP, NPC, NP-Hard (relation based on $P \neq NP$, $P = NP$)
- ▶ Prove a DEC is in NP.
- ▶ Three classes: P, NP, NPC (Also NP-hard)
- ▶ Polynomial reduction $A \leq_p B$ is to show any algorithm that solves B can be used to define an algorithm that solves A . (A is no harder than B or B is at least as hard as A .)
- ▶ Important NP-complete problems: SAT, 3SAT, VC, HC, PARTITION, 3DM, CLIQUE, COLOR, KNAPSACK, HS
- ▶ **Test of your understanding of the complexity classes**
 - ▶ If $\Pi_1 \leq_p \Pi_2$ and $\Pi_1 \in \mathbf{NP}$, is $\Pi_2 \in \mathbf{NP}$?
 - ▶ If $\Pi_1 \leq_p \Pi_2$ and $\Pi_1, \Pi_2 \in \mathbf{NPC}$, is $\Pi_2 \leq_p \Pi_1$?
 - ▶ If $\Pi_1 \leq_p \Pi_2$ and $\Pi_1 \notin \mathbf{NP}$, is $\Pi_1 \in \mathbf{P}$?
 - ▶ If $\Pi_1 \leq_p \Pi_2$ and $\Pi_2 \leq_p \Pi_1$, then $\Pi_1, \Pi_2 \in \mathbf{NPC}$.
 - ▶ If $\Pi_1, \Pi_2 \in \mathbf{NPC}$, then $\Pi_1 \leq_p \Pi_2$, and $\Pi_2 \leq_p \Pi_1$.

Some sample problems

- ▶ The universal language, A_{TM} , is a proper (non-equal) subset of the halting language, $HALT_{TM}$.
- ▶ The Post Correspondence Problem is decidable for the unary alphabet.
- ▶ If L is TR but non-TD, then \bar{L} is non-TR.

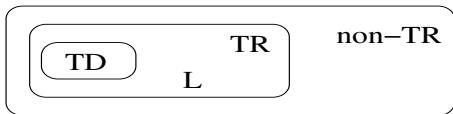


Figure 6: Venn diagram for TD, TR, and non-TR

- ▶ If A is non-TD, $A \leq C$, $D \leq C$, then D must be non-TR. F (because D may be TD or TR)

A proof that 3SAT is NP-complete:

First, 3SAT is obvious in **NP**.

Next, we show that $\text{SAT} \leq_p \text{3SAT}$.

Given any instance of SAT, $f(x_1, \dots, x_n) = c_1 \wedge \dots \wedge c_m$, where c_i is a disjunction of literals. To construct an instance for 3SAT, we need to convert any c_i to an equivalent c'_i , a conjunction of clauses with exactly 3 literals.

Case 1. If $c_i = z_1$ (one literal), define y_i^1 and y_i^2 . Let $c'_i = (z_1 \vee y_i^1 \vee y_i^2) \wedge (z_1 \vee y_i^1 \vee \neg y_i^2) \wedge (z_1 \vee \neg y_i^1 \vee y_i^2) \wedge (z_1 \vee \neg y_i^1 \vee \neg y_i^2)$.

Case 2. If $c_i = z_1 \vee z_2$ (two literals), define y_i^1 . Let $c'_i = (z_1 \vee z_2 \vee y_i^1) \wedge (z_1 \vee z_2 \vee \neg y_i^1)$.

Case 3. If $c_i = z_1 \vee z_2 \vee z_3$ (three literals), let $c'_i = c_i$.

Case 4. If $c_i = z_1 \vee z_2 \vee \dots \vee z_k$ ($k > 3$), define $y_i^1, y_i^2, \dots, y_i^{k-3}$. Let $c'_i = (z_1 \vee z_2 \vee y_i^1) \wedge (\neg y_i^1 \vee z_3 \vee y_i^2) \wedge (\neg y_i^2 \vee z_4 \vee y_i^3) \wedge \dots \wedge (\neg y_i^{k-3} \vee z_{k-1} \vee z_k)$.

If c_i is satisfiable, then there is a literal $z_l = T$ in c_i . If $l = 1, 2$, let $y_i^1, \dots, y_i^{k-3} = F$. If $l = k - 1, k$, let $y_i^1, \dots, y_i^{k-3} = T$. If $3 \leq l \leq k - 2$, let $y_i^1, \dots, y_i^{l-2} = T$ and $y_i^{l-1}, \dots, y_i^{k-3} = F$. So c'_i is satisfiable.

If c'_i is satisfiable, assume $z_l = F$ for all $l = 1, \dots, k$. Then $y_i^1, \dots, y_i^{k-3} = T$. So the last clause $(\neg y_i^{k-3} \vee z_{k-1} \vee z_k) = F$. Therefore, c'_i is not satisfiable. Contradiction.

The instance of 3SAT is therefore $f'(x_1, \dots, x_n, \dots) = c'_1 \wedge \dots \wedge c'_m$, and f is satisfiable if and only if f' is satisfiable.

Cook's Theorem: SAT is **NP**-complete.

Proof. SAT is clearly in **NP** since a NTM exists that guesses a truth assignment and verifies its correctness in polynomial time. Now we wish to prove $\forall \Pi \in \mathbf{NP}, \Pi \leq_p \text{SAT}$, or equivalently, for any polynomial-time NTM M , $L(M) \leq_p L_{\text{SAT}}$.

For any NTM M , assume $Q = \{q_0, q_1(\text{accept}), q_2(\text{reject}), \dots, q_r\}$ and $\Gamma = \{s_0, s_1, s_2, \dots, s_v\}$. Also assume that the time is bounded by $p(n)$, where n is the length of the input.

We wish to prove that there is a function

$f_M : \Sigma^* \rightarrow \{\text{instances of SAT}\}$ such that $\forall x \in \Sigma^*, x \in L(M)$ iff $f_M(x)$ is satisfiable. In other words, we wish to use a Boolean expression $f_M(x)$ to describe the computation of M on x .

Variables in $f_M(x)$:

— State: $Q[i, k]$. M is in q_k after the i th step of computation (at time i).

— Head: $H[i, j]$. Head points to tape square j at time i .

— Symbol: $S[i, j, l]$. Tape square j contains s_l at time i .

(Assume the tape is one-way infinite and the leftmost square is labeled with 0.)

For example, initially $i = 0$. Assume the configuration is $q_0 abba$.

Let $s_0 = B$, $s_1 = a$, and $s_2 = b$. Therefore, we set the following

Boolean variables to be true: $Q[0, 0]$, $H[0, 0]$, $S[0, 0, 1]$,

$S[0, 1, 2]$, $S[0, 2, 2]$, $S[0, 3, 1]$ and $S[0, j, 0]$ for $j = 4, 5, \dots$. A

configuration defines a truth assignment, but not vice versa.

Clauses in $f_M(x)$:

— At any time i , M is in exactly one state.

$Q[i, 0] \vee \dots \vee Q[i, r]$ for $0 \leq i \leq p(n)$.

$\neg Q[i, k] \vee \neg Q[i, k']$ for $0 \leq i \leq p(n)$ and $0 \leq k < k' \leq r$.

— At any time i , head is scanning exactly one square.

$H[i, 0] \vee \dots \vee H[i, p(n)]$ for $0 \leq i \leq p(n)$.

$\neg H[i, j] \vee \neg H[i, j']$ for $0 \leq i \leq p(n)$ and $0 \leq j < j' \leq p(n)$.

— At any time i , each square contains exactly one symbol.

$S[i, j, 0] \vee \dots \vee S[i, j, v]$ for $0 \leq i \leq p(n)$ and $0 \leq j \leq p(n)$.

$\neg S[i, j, l] \vee \neg S[i, j, l']$ for $0 \leq i \leq p(n)$, $0 \leq j \leq p(n)$ and

$0 \leq l < l' \leq v$.

— At time 0, M is in its initial configuration. Assume

$$x = s_{l_1} \cdots s_{l_n}.$$

$$Q[0, 0].$$

$$H[0, 0].$$

$$S[0, 0, l_1], \dots, S[0, n-1, l_n].$$

$$S[0, j, 0] \text{ for } n \leq j \leq p(n).$$

— By time $p(n)$, M has entered q_1 (accept). (If M halts in less than $p(n)$ steps, additional moves can be included in the transition function.)

$$Q[p(n), 1].$$

— Configuration at time $i \rightarrow$ configuration at time $i + 1$. Assume $\delta(q_k, s_l) = (q_{k'}, s_{l'}, D)$, where $D = -1, 1$.

If the head does not point to square j , symbol on j is not changed from time i to time $i + 1$.

$H[i, j] \vee \neg S[i, j, l] \vee S[i + 1, j, l]$ for $0 \leq i \leq p(n)$, $0 \leq j \leq p(n)$, and $0 \leq l \leq v$.

If the current state is q_k , the head points to square j which contains symbol s_l , then changes are made accordingly.

$\neg H[i, j] \vee \neg Q[i, k] \vee \neg S[i, j, l] \vee H[i + 1, j + D]$,

$\neg H[i, j] \vee \neg Q[i, k] \vee \neg S[i, j, l] \vee Q[i + 1, k']$, and

$\neg H[i, j] \vee \neg Q[i, k] \vee \neg S[i, j, l] \vee S[i + 1, j, l']$, for $0 \leq i \leq p(n)$, $0 \leq j \leq p(n)$, $0 \leq k \leq r$, and $0 \leq l \leq v$.

Let $f_M(x)$ be the conjunction of all the clauses defined above. Then $x \in L(M)$ iff there is an accepting computation of M on x iff $f_M(x)$ is satisfiable. f_M can be computed in polynomial time since $|f_M(x)| \leq (\text{number of clauses}) * (\text{number of variables}) = O(p(n)^2) * O(p(n)^2) = O(p(n)^4)$. So there is a polynomial reduction from any language in **NP** to SAT. So SAT is **NP**-complete.