

Discrete-Event Simulation: A First Course

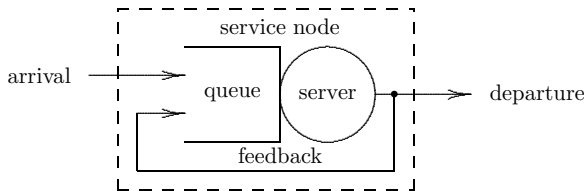
Section 3.3: Discrete-Event Simulation Examples

Outline

- Single-server service node with immediate feedback
- A simple inventory system with delivery lag
- A single-server machine shop

SSQ with Immediate Feedback

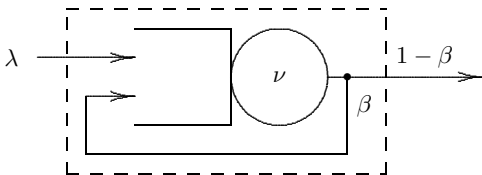
- If the service a job receives is incomplete or unsatisfactory, the job feeds back



- Completion of service and departure now have different meanings

Model Considerations

- When feedback occurs the job joins the queue consistent with the queue discipline
- The decision to depart or feed back is random with *feedback probability* β



- λ is the arrival rate
- ν is the service rate

Model Considerations

- Feedback is independent of past history
- In theory, a job may feed back arbitrarily many times
- Typically β is close to 0.0

GetFeedback Method

```
int GetFeedback(double beta)    /* 0.0 <= beta < 1.0 */
{
    SelectStream(2);
    if (Random() < beta)
        return (1);           /* feedback occurs */
    else
        return (0);           /* no feedback */
}
```

Statistical Considerations

- Index $i = 1, 2, 3, \dots$ counts jobs that enter the service node
 - fed-back jobs are not recounted
- Using this indexing, all job-averaged statistics remain valid
 - We must update delay times, wait times, and service times *for each feed back*
- Jobs from outside the system are merged with jobs from the feedback process
- The steady-state request-for-service rate is larger than λ by the positive additive factor $\beta\bar{x}\nu$
- Note that \bar{s} increases with feedback but $1/\nu$ is the average service time per request

Algorithm and Data Structure Considerations

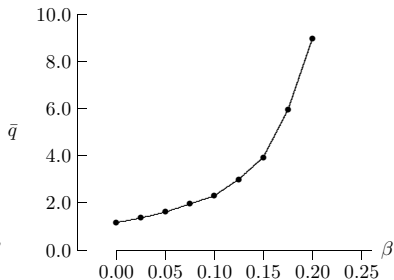
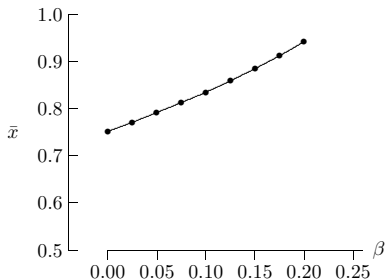
● Example 3.3.1

job index	1	2	3	4	5	·	6	·	7	8	·	9	...
arrival/													
feedback	1	3	4	7	10	13	14	15	19	24	26	30	...
service	9	3	2	4	7	5	6	3	4	6	3	7	...
completion	10	13	15	19	26	31	37	40	44	50	53	60	...

- At the computational level, some algorithm and data structure is necessary

Example 3.3.2

- Program ssq2 was modified to incorporate immediate feedback
 - Interarrivals = *Exponential*(2.0)
Service times = *Uniform*(1.0, 2.0)



- It appears saturation is achieved as $\beta \rightarrow 0.25$

Flow Balance and Saturation

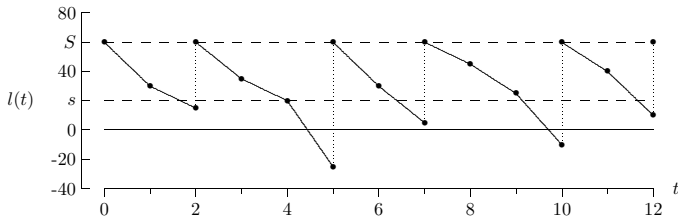
- Jobs flow into the service node at the average rate of λ
- To remain flow balanced jobs must flow out of the service node at the same average rate
- The average rate at which jobs flow out of the service node is

$$\bar{x}(1 - \beta)\nu$$

- Flow balance is achieved when $\lambda = \bar{x}(1 - \beta)\nu$
- Saturation occurs when $\bar{x} = 1$ or as $\beta \rightarrow 1 - \lambda/\nu = 0.25$

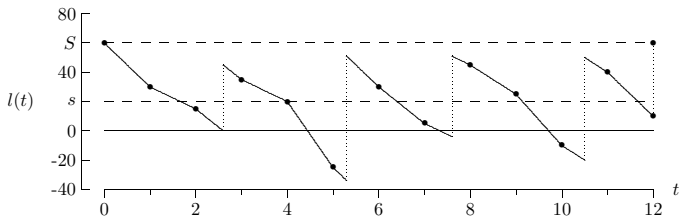
Simple Inventory System with Delivery Lag

- *Delivery lag* or *lead time* occurs when orders are not delivered immediately
- Lag is assumed to be random and independent of order size
- Without lag, inventory jumps occur only at inventory review times



SIS with Lag

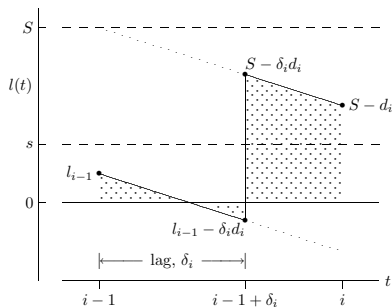
- With delivery lag, inventory jumps occur at arbitrary times



- The last order is assumed to have no lag
- We assume that orders are delivered before the next inventory review
- With this assumption, there is no change to the specification model

Statistical Considerations

- If $l_{i-1} \geq s$ the equations for \bar{l}_i^+ and \bar{l}_i^- remain correct
- When delivery lag occurs the time-averaged holding and shortage intervals must be modified
 - The delivery lag for interval i is $0 < \delta_i < 1$



Consistency Checks

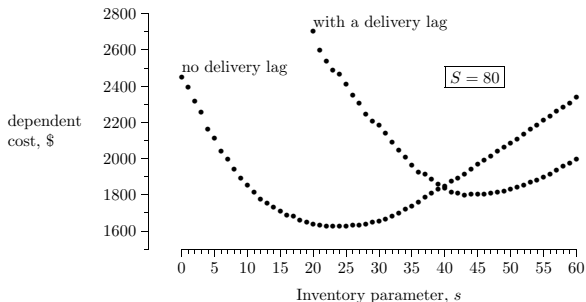
- It is fundamentally important to verify extended models with the parent model
 - Set system parameters to special values
- Set $\beta = 0$ for the SSQ with feedback
 - Verify that all statistics agree with parent
- Using the library `rnrgs` facilitates this kind of comparison
- It is a good practice to check for intuitive “small-perturbation” consistency
 - Use a small, but non-zero β and check that appropriate statistics are slightly larger

Example 3.3.3

- For the SIS with delivery lag, $\delta_i = 0.0$ iff no order during i^{th} interval, $0 < \delta_i < 1.0$ otherwise
- The SIS is *lag-free* iff $\delta_i = 0.0$ for all i
- If (S, s) are fixed then, even with small delivery lags:
 - \bar{o} , \bar{d} , and \bar{u} are the same regardless of delivery lag
 - Compared to the lag-free system, \bar{l}^+ will decrease
 - Compared to the lag-free system, \bar{l}^- will increase or remain unchanged

Example 3.3.4

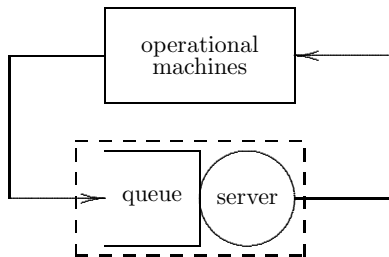
- Delivery lags are independent $Uniform(0.0, 1.0)$ random variates



- Delivery lag causes \bar{I}^+ to decrease and \bar{I}^- to increase or remain the same
- $C_{\text{hold}} = \$25$ and $C_{\text{short}} = \$700$ cause shift up and to the left

Single-Server Machine Shop

- The machine shop model is closed because there are a finite number of machines in the system



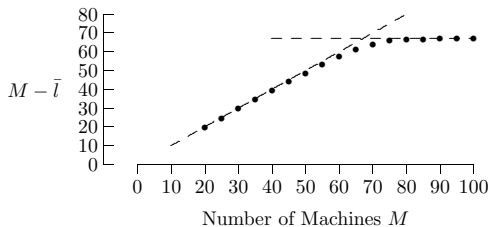
- Assume repair times are $Uniform(1.0, 2.0)$ random variates
- There are M machines that fail after an $Exponential(100.0)$ random variate

Program ssms

- Program `ssms` simulates a single-server machine shop
- The library `rngs` is used to uncouple the random processes
- The failure process is defined by the array `failures`
 - A $\mathcal{O}(M)$ search is used to find the next failure
 - Alternate data structures can be used to increase computational efficiency

Example 3.3.5

- The time-averaged number of working machines is $M - \bar{l}$



- For small values of M the time-averaged number of operational machines is essentially M
- For large values of M this value is essentially constant at approximately 67