

# Discrete-Event Simulation: A First Course

## Section 8.4: Batch Means

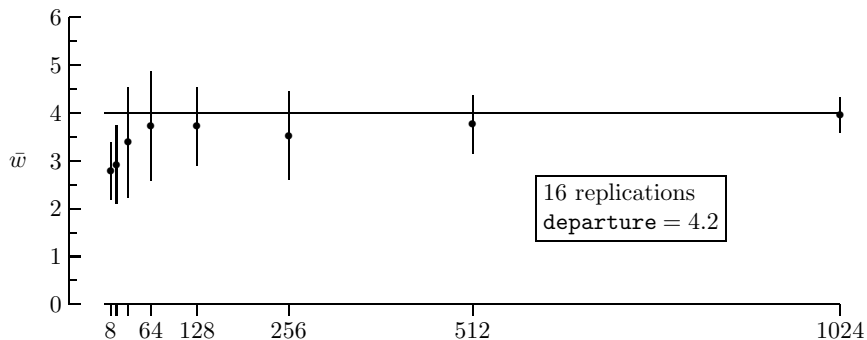
## Section 8.4: Batch Means

- Two types of DES models: transient and steady-state
- For transient, construct interval estimates using *replication*
- For steady-state, obtain *point* estimate by simulating for a long time
- Can we obtain *interval* estimates for steady-state statistics?  
→ *use method of batch means*

## Example 8.4.1: Transient vs. Steady-State Estimates

- Program `ssq2` was modified to simulate an  $M/M/1$  with  $\lambda = 1.0$  and  $\nu = 1.25$
- For an  $M/M/1$ , analytically:
  - Steady-state utilization is  $\rho = \lambda/\nu = 0.8$  (Section 8.5)
  - Expected steady-state wait is  $E[W] = 4$
- Can *transient* estimates be accurate *steady-state* estimates?
- Eliminate the initial state bias by setting departure to 4.2
- Use 16 replications to construct transient interval estimates for 8, 16, 32,  $\dots$ , 1024 jobs

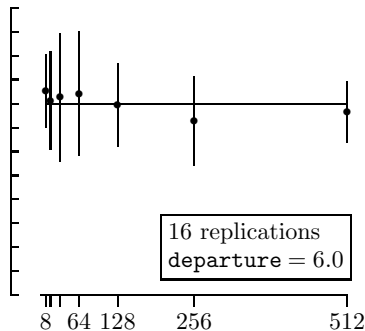
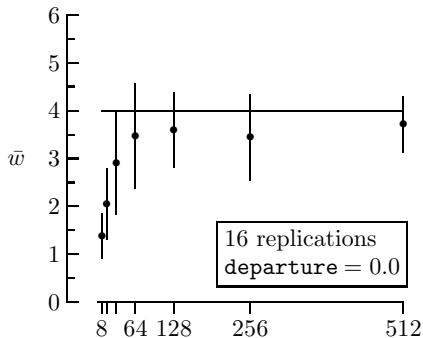
# Example 8.4.1: Transient vs. Steady-State Estimates



- *Finite-horizon* interval estimates can be accurate *steady-state* estimates (provided the number of jobs is not small)

# Example 8.4.2: Initial State Bias

- Consider initial values of 0.0 and 6.0 for departure
  - Most likely steady-state condition is an idle node (0.0)
  - The value 6.0 chosen by experimentation



## Example 8.4.2: Observations

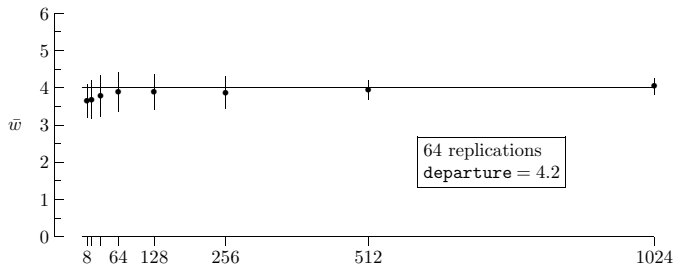
- departure = 0.0: initial state can have significant impact
- departure = 6.0: possible to choose an initial state that eliminates the initial state bias
- When the number of jobs is large, estimates are very good and essentially *independent* of the initial state

# Interval Estimates for Steady-State

- Use replication-based *transient* interval estimates
- Each replication must correspond to a long simulated time period
- Three issues:
  - What is the initial state?
  - What is the length of the simulated time?
  - How many replications?
- Previous example provides insight into first two issues

# Example 8.4.3: Increase the Number of Replications

- Repeat the previous experiments using 64 replications
- All other parameters remain the same

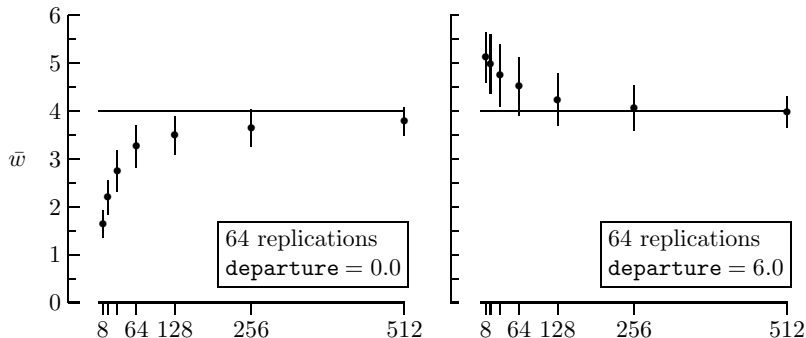




## Example 8.4.3: Observations

- The interval estimates have been cut approximately in half
- Initial state bias eliminated by using  $\text{departure} = 4.2$   
*Even for a small number of jobs!*
- The initial state bias that *seemed* to be evident before (16 replications) was natural small-sample variation
- Note: we were able to avoid initial state bias only because we already knew  $E[W]$

# Example 8.4.4: Increase the Number of Replications



- That departure = 6.0 seemed right was a false impression based on misleading small-sample statistics

# Summary

- Want interval estimates for steady-state
- Replicated transient statistics can be used
- However, initial bias problem
- Need technique that avoids the initial bias problem

# Method of Batch Means

- Previously, each replication was initialized with *same state*
- Gives initial bias problem
- *Batch means*:
  - Make *one* long run and partition into *batches*
  - Compute an average statistic for each batch
  - Construct an interval estimate using the batch means
- Initial state bias is eliminated
- State at the beginning of each batch is the state at the end of previous batch

# Algorithm 8.4.1: Method of Batch Means

## Algorithm 8.4.1

Consider a sequence of samples  $x_1, x_2, \dots, x_n$

1. Select a *batch size*  $b > 1$
2. Group the sequence into  $k$  batches

$$\underbrace{x_1, x_2, \dots, x_b}_{\text{batch 1}}, \underbrace{x_{b+1}, x_{b+2}, \dots, x_{2b}}_{\text{batch 2}}, \underbrace{x_{2b+1}, x_{2b+2}, \dots, x_{3b}, \dots}_{\text{batch 3}}$$

and for each calculate the *batch mean*

$$\bar{x}_j = \frac{1}{b} \sum_{i=1}^b x_{(j-1)b+i} \quad j = 1, 2, \dots, k$$

3. Compute  $\bar{x}$  and  $s$  of batch means  $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_k$

# Algorithm 8.4.1: Method of Batch Means

## Algorithm 8.4.1

4. Pick a *level of confidence*  $1 - \alpha$  (typically  $\alpha = 0.05$ )
5. Calculate the critical value  $t^* = \text{idfStudent}(k - 1, 1 - \alpha/2)$
6. Calculate the interval endpoints  $\bar{x} \pm t^*s/\sqrt{k - 1}$ 
  - $(1 - \alpha) \times 100\%$  confident that the true *unknown* steady-state mean lies in the interval
  - Provided  $b$  is large, true *even if the sample is autocorrelated*

# Effect of Batch Parameters

- Provided no points are discarded:

$$\bar{x} = \frac{1}{k} \sum_{j=1}^k \bar{x}_j = \frac{1}{n} \sum_{i=1}^n x_i$$

- Choice of  $(b, k)$  has *no* impact on the *point* estimate
- Only the width of the *interval* estimate is affected

## Example 8.4.5: Effect of $(b, k)$

- Consider an initially idle  $M/M/1$  with  $(\lambda, \nu) = (1, 1.25)$
- Use `ssq2` to generate  $n = 32768$  consecutive waits
- Using batch means with different  $(b, k)$ :

$(b, k)$	(8, 4096)	(64, 512)	(512, 64)	(4096, 8)
$\bar{w}$	$3.94 \pm 0.11$	$3.94 \pm 0.25$	$3.94 \pm 0.29$	$3.94 \pm 0.48$

- Note that 3.94 is independent of  $(b, k)$
- Width of the interval estimate is not



# Is the Method of Batch Means Valid?

- For interval estimation, the batch means must be *iid Normal*
  1. Are the batch means *Normal*?

*As  $b$  increases, mean of  $b$  RVs tends to Normal*
  2. Is the data actually independent?

*Autocorrelation (Section 4.4) becomes zero if  $b$  is large*
- Therefore, as  $b$  increases, method of batch means becomes increasingly more valid

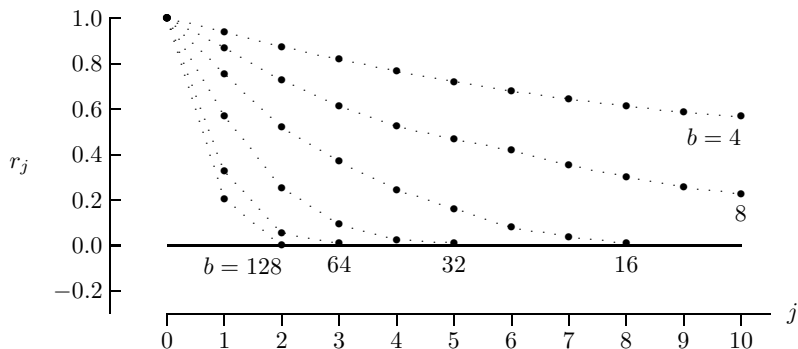
# Guidelines for Choosing $(b, k)$

- Note: If  $b$  is too large,  $k$  will be small giving wide interval estimates
- Number of batches  $k$ :
  - Avoid small-sample variation
  - $k \geq 32$ ;  $k = 64$  is recommended
- Batch size  $b$ :
  - Want to ensure (approximate) independence
  - $b$  should be at least twice the autocorrelation "cut-off" lag (Section 4.4)

## Example 8.4.6: Achieving Independence

- Consider an  $M/M/1$  with steady-state  $\bar{x} = \lambda/\nu = 0.8$
- The effective cut-off lag is 128
- Choose  $b = 256$  to ensure independent batch means
- Graph the autocorrelation function  $r_j$  versus the lag  $j$

# Example 8.4.6: Achieving Independence



- As  $b$  increases, autocorrelation is reduced
- For  $b = 128$ , no autocorrelation for  $j > 1$

## Example 8.4.6: Summary

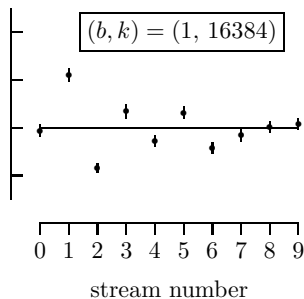
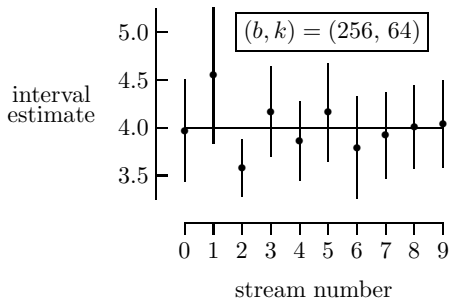
- Consider  $M/M/1$  with steady-state  $\bar{x} = \lambda/\nu = 0.8$
- Use  $k = 64$  batches of size  $b = 256$
- The batch mean interval estimate will contain  $E[W]$  with probability  $1 - \alpha$
- $n = bk = 16384$  jobs required to produce this estimate
- If  $\lambda/\nu$  were larger,  $n$  must be larger

# Batch Means as a “Black Box”

- Can apply Algorithm 8.4.1 for *any* reasonable  $(b, k)$
- Experiment with increasing  $(b, k)$  until “convergence”
  - Set  $k = 64$ , and then successively double  $b$
- Convergence: significant overlap in a sequence of increasingly more narrow interval estimates

# Example 8.4.7: "Black Box"

- Consider  $M/M/1$  with  $(\lambda, \nu) = (1.00, 1.25)$
- Produce 10 interval estimates using batch means



## Example 8.4.7: “Black Box” Observations

- (256, 64): All but one brackets theoretical  $E[W]$
- (1, 16384): Intervals are too small  
False sense of confidence (30% instead of 95%)
- Failure to correctly batch the data can lead to unrealistically small variance estimates
- Iteration: fix  $k$  and increase  $b$  until enough intervals overlap  
Remember that  $n = bk$