


## The Four Steps of Modeling

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- General structure of the analysis result
- "Architecture" or " model class"
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Apply the algorithm

- Compare models through the score function
- But: How do we find the models?


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## Apply the algorithm

- Compare models through the score function
- But: How do we find the models?

Validate the results

- We know: Best model among the chose ones
- But: Is this the best among very good or very bad choices?
- Model $=$ The form or structure of the analysis result
- Here the parameters are not defined only the type is selected
- Examples:
- Linear models $(y=a x+b)$
- Constant values (e.g. mean)
- Rule based models (if A buys product one, then weather is sunny)


## Model class - Requirements

## Simplicity

- Occam's razor:
- Choose the simplest model that still "explains" the data.
- Or: Numquam ponenda est pluralitas sine necessitate
$=$ [Plurality must never be posited without necessity]
- easier to understand
- lower complexity
- avoid overfitting(see Slide 21 ff.)


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Interpretability

- Black-Boxes are mostly not a proper choice
- But: They can result in a very good accuracy(e.g. neural networks)


## Global vs. local models

- Global models provide a (not necessarily good) description for the whole data set.
Example: Regression line
- Local models or patterns provide a description for only a part or subset of the data set.
Example: Association rules
- find an objective function $f: \mathcal{M} \rightarrow \mathbb{R}$
- Which, evaluates the quality of your model
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## Example

Given: Dataset $D=\left\{d_{1}, d_{2}, \ldots d_{n}\right\} \in \mathbb{R}^{m}$ and " model" $\mathcal{M}: \mathbb{R}^{m} \rightarrow \mathbb{R}^{m}$ ( $\mathcal{M}$ predicts a value for a given data point).

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- Mean squared error : $f(x)=\frac{1}{n} \sum_{i=1}^{n}(x-\mathcal{M}(x))^{2}$
- find an objective function $f: \mathcal{M} \rightarrow \mathbb{R}$
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- Mean absolute error : $f(x)=\frac{1}{n} \sum_{i=1}^{n}|x-\mathcal{M}(x)|$

Short comment: What is classification?

## Example

Imagine a cup factory, which wants to classify their cups as good or broken.


## Error functions for classification problems

How to set up an error function for those classification problems?

- Very common misclassification rate $=\frac{\# \text { wrong classified }}{\# \text { total classified }}$
- A low misclassification rate does not necessarily tell anything about the quality of a classifier.
- when classes are unbalanced (e.g. When 99\% of the production are ok, a classifier always predicting ok will have a misclassification rate of $1 \%$.)


## Cost matrix

- More general approach than the misclassification rate: cost function or cost matrix.
- The consequences (costs) for misclassification for one class might be different than for another class.


## Example

Tea cup production.

|  |  | predicted class |  |
| :---: | :---: | :---: | :---: |
| Cost matrix | true class | OK | broken |
|  | OK | 0 | $c_{1}$ |
|  | broken | $c_{2}$ | 0 |

## Cost matrix

General form of a cost matrix for a multi-class classification problem:

|  | predicted class |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| true class | $c_{1}$ | $c_{2}$ | $\ldots$ | $c_{m}$ |
| $c_{1}$ | 0 | $c_{1,2}$ | $\ldots$ | $c_{1, m}$ |
| $c_{1}$ | $c_{2,1}$ | 0 | $\ldots$ | $c_{2, m}$ |
| $\vdots$ | $\vdots$ | $\vdots$ | $\ddots$ | $\vdots$ |
| $c_{m}$ | $c_{m, 1}$ | $c_{m, 2}$ | $\ldots$ | 0 |

## Cost matrix

When such a cost matrix is provided, the expected loss given by

$$
\operatorname{loss}\left(c_{i} \mid E\right)=\sum_{j=1}^{m} P\left(c_{j} \mid E\right) c_{j i}
$$

should be minimized.

- $E$ is the evidence, i.e. the observed values of the predictor attributes used for the classification.
- $P\left(c_{j} \mid E\right)$ is the predicted probability that the true class is $c_{j}$ given observation $E$.


## Cost matrix

## Example

(Hypothetical) cost matrix for the tea cup production problem

| true class | OK | broken |
| :---: | :---: | :---: |
| OK | 0 | 1 |
| broken | 10 | 0 |

A classifier might classify a specific cup with $80 \%$ to the class ok and with $20 \%$ to the class broken.

- Expected loss for choosing ok: $0.8 \cdot 0+0.2 \cdot 10=2$.
- Expected loss for choosing broken: $0.8 \cdot 1+0.2 \cdot 0=0.8$.

Choose broken in this case to minimize the expected loss!

## Cost matrix

Using the cost matrix

|  | predicted class |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| true class | $c_{1}$ | $c_{2}$ | $\ldots$ | $c_{m}$ |
| $c_{1}$ | 0 | 1 | $\ldots$ | 1 |
| $c_{1}$ | 1 | 0 | $\ldots$ | 1 |
| $\vdots$ | $\vdots$ | $\vdots$ | $\ddots$ | $\vdots$ |
| $c_{m}$ | 1 | 1 | $\ldots$ | 0 |

corresponds to minimising the misclassification rate.

## Algorithms for model fitting

The objective function (scoring function) for models

- does not tell us how to find the best or a good model,
- it only provides a means for comparing models.

Optimisation algorithms to find the best or at least a good model are needed.

## Closed form solutions

In the best case, an explicit solution can be provided.

## Example

Find a regression line $y=a x+b$ that minimizes the mean square error for the data set $\left(x_{1}, y_{1}\right), \ldots,\left(x_{n}, y_{n}\right)$. Computing partial derivatives of the objective (error) function

$$
E(a, b)=\frac{1}{n} \sum_{i=1}^{n}\left(a x_{i}+b-y_{i}\right)^{2}
$$

w.r.t. the paramaters $a$ and $b$ yields

$$
\begin{aligned}
& \frac{\partial E}{\partial a}=\frac{2}{n} \sum_{i=1}^{n}\left(a x_{i}+b-y_{i}\right) x_{i}=0 \\
& \frac{\partial E}{\partial b}=\frac{2}{n} \sum_{i=1}^{n}\left(a x_{i}+b-y_{i}\right)=0
\end{aligned}
$$

## Closed form solutions

## Example

The solution of this system of equations is

$$
\begin{aligned}
a & =\frac{n \sum_{i=1}^{n} x_{i} y_{i}-\left(\sum_{i=1}^{n} x_{i}\right)\left(\sum_{i=1}^{n} y_{i}\right)}{n \sum_{i=1}^{n} x_{i}^{2}-\left(\sum_{i=1}^{n} x_{i}\right)^{2}} \\
b & =\bar{y}-a \bar{x}
\end{aligned}
$$

where $\bar{x}=\frac{1}{n} \sum_{i=1}^{n} x_{i}$ and $\bar{y}=\frac{1}{n} \sum_{i=1}^{n} y_{i}$.

## Algorithms for model fitting

For differentiable score functions, a gradient methods can be applied.


A landscape for the mean squared error.

$k=2$
A landscape with many local minima and maxima

$k>2$
The objective function corresponds to a landscape in ( $k+1$ ) dimensional space.

Problems

- Will only find local optima.
- Parameters (step width) must be adjusted or computed in each iteration step.
- For discrete problems with a finite search space (like finding association rules), combinatorial optimization strategies are needed.
- In principle, an exhaustive search of the finite domain $\mathcal{M}$ is possible, however, in most cases it is not feasible, since $\mathcal{M}$ is much too large.


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## Example

- Finding the best possible association rules with an underlying set of 1000 items (products).
- Every combination of items, i.e. every nonempty subset is a possible candidate set from which several rules may be constructed.
- The number of nonempty subsets alone contains $2^{1000}-1>10^{300}$ elements.

Heuristic strategies are therefore needed.

- Random search. Create random solutions and choose the best one among them.


## Very inefficient

- Greedy strategies. Formulate an algorithm that tries to improve the solution in each step.
- Example. Gradient method.
- Example. Hillclimbing.

Start with a random solution,
generate new solutions in the "neighbourhood" of the solution.
If a new solution is better than the old one, generate new solutions in its "neighbourhood".

Can find a solution quickly, but get stuck in local optima.

- Simulated annealing is a mixture between random search and a greedy strategy. Simulated annealing is a modified version of hillclimbing, sometimes replacing better solutions by worse ones with a (low) probability.
This probability is decreased in each iteration step.

Algorithms for model fitting: Heuristic strategies

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- Evolutionary algorithms like evolution strategies or genetic algorithms combine random with greedy components, using a population of solutions in order to explore the search space in parallel and efficiently.
- Alternating optimisation can be applied when the set of parameters can be split into disjoint subsets in such a way that for each subset an analytical solution for the optimum can be provided, given the parameters in the other subsets are fixed. Alternating optimization computes the analytical solution for the parameter subsets alternatingly and iterates this scheme until convergence.


## Good fit to data is not necessarily the same as a good fit to concept!



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## Overfitting

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## Overfitting

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Fitting the noise rather than fitting the underlying relationship.
Typical indicator for overfitting: "Perfect fit" e.g. the error gets near to zero.
ONE solution: Choose a less flexible model.


## Model error

- There are 4 parts of potential error origins, which sum up to the overall error meassure
- Error $=\quad$ Experimental error
+ Sample error
+ Model error
+ Algorithmic error


## Experimental Error

- The pure error or experimental error is inherent in the data and due to noise, random variations, imprecise measurements or the influence of hidden variables that cannot be observed.
- It is impossible to overcome this error by the choice of a suitable model.
- Also called intrinsic error.
- In the context of classification problems it is also called Bayes error.

How can a classifier be judged when no explicit cost matrix is known and the misclassification rate might not be a good choice?

Consider a two class problem. (positive and negative)

Very often, classifiers provide a score for each class.
e.g. a likelihood

## Example

Assume, only the attribute Sepal Length should be used to distinguish Iris versicolor from Iris virginica by a simple rule of the form

If Sepal Length $<c$, then versicolor, otherwise virginica
where $c$ can be chosen in the range of the values of the attribute Sepal Length.

The attribute Sepal Length provides the "score" in this case.

| S. Length | Species | S. Length | Species | S. Length | Species |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 4.9 | versicolor | 5.6 | versicolor | 5.9 | versicolor |
| 4.9 | virginica | 5.6 | versicolor | 5.9 | versicolor |
| 5.0 | versicolor | 5.6 | virginica | 5.9 | virginica |
| 5.0 | versicolor | 5.7 | versicolor | 6.0 | versicolor |
| 5.1 | versicolor | 5.7 | versicolor | 6.0 | versicolor |
| 5.2 | versicolor | 5.7 | versicolor | 6.0 | versicolor |
| 5.4 | versicolor | 5.7 | versicolor | 6.0 | versicolor |
| 5.5 | versicolor | 5.7 | versicolor | 6.0 | virginica |
| 5.5 | versicolor | 5.7 | virginica | 6.0 | virginica |
| 5.5 | versicolor | 5.8 | versicolor | 6.1 | versicolor |
| 5.5 | versicolor | 5.8 | versicolor | 6.1 | versicolor |
| 5.5 | versicolor | 5.8 | versicolor | 6.1 | versicolor |
| 5.6 | versicolor | 5.8 | virginica | 6.1 | versicolor |
| 5.6 | versicolor | 5.8 | virginica | 6.1 | virginica |
| 5.6 | versicolor | 5.8 | virginica | $\vdots$ | $\vdots$ |

- Consider versicolor as the "positive" and virginica as the "negative" class.
- The higher the threshold $c$ is chosen, the more instances are classified as "positive" (versicolor).
- there are four possibilities :
- true positive TP classified as Pos and is Pos
- false positive FP classified as Pos and is Neg
- true negative TN classified as Neg and is Neg
- false negative FN classified as Neg and is Pos
- Increasing the threshold $c$, will increase the true positives as well as the true negatives.
- Ideal case: only true positives and no false negatives

The ROC curve (receiver operating characteristic curve) draws the false positive rate against the false negative rate (depending on the choice of the threshold $c$ ).



A ROC curve of a better performing and a classifier with a performance. The area under curve (AUC), i.e. the area under the ROC curve, is an indicator how well the classifier solves the problem. The larger the area, the better the solution for the classification problem.

## Confusion matrix

A confusion matrix is a table where the rows represent the true classes and the columns the predicted classes. Each entry specifies how many objects from a given class are classified into the class of the corresponding column.

| true class | predicted class |  |  |
| :---: | :---: | :---: | :---: |
|  | Iris setosa | Iris versicolor | Iris virginica |
| Iris setosa | 50 | 0 | 0 |
| Iris versicolor | 0 | 47 | 3 |
| Iris virginica | 0 | 2 | 48 |

A possible confusion matrix for the Iris data set

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- The smaller the sample the smaller the probability for a perfect model


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There are different models for the data

- simpler model $\Longrightarrow$ bigger error
- more complex model $\Longrightarrow$ overfitting and larger error on new data
- type of model $\Longrightarrow$ different " fit" to data


## Algorithmic Error

- Based on the selected algorithm


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- (otherwise : choose another)

Machine Learners have a slightly different view:

- Machine Learning Bias: Model and Algorithmic Error
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Alternative View: Error Decomposition:

$$
M S E=\operatorname{Var}\left(\theta^{*}\right)+\left(\operatorname{Bias}\left(\theta^{*}\right)\right)^{2}
$$

( $\theta^{*}$ is an estimator for unknown parameter(s) $\theta$. MSE: Mean Squared Error)

- Can we find a good model without model or algorithmic bias?
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- Remember? Version Space Learning

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We cannot learn without a bias

- The error for unseen data will most probably always be bigger than for the data used for training.
- How do we find out which model is actually suited best to our problem?



## Training and Test Data

- Split data into two subsets: training and test data
- Train your model on the training data and measure the model quality on the test data
- Typically $2 / 3$ training $1 / 3$ test (usually more training)
- Splitting strategies
- Random (distribution in both sets should be roughly same)
- Stratification (i.e. the distribution of one class should remain)
- Split into training, test and validation
- Choose for each model kind the best based on the test data
- Test the best models on the validation data set.


## Validation of Models

Estimating the Generalization ability of a Model using a separate data set $T_{\text {eval }}$

$$
\begin{gathered}
T=T_{\text {train }}^{\cup} T_{\text {eval }} \\
T_{\text {train }} \cap T_{\text {eval }}=\emptyset \\
P(E)=\approx \frac{\sum_{x \in T_{\text {eval }}} g(H(x), C(x))}{\left|T_{\text {eval }}\right|} \\
g(x, y)=1 \text { if } x=y \text { and } g(x, y)=0 \text { if } x \neq y
\end{gathered}
$$

- Split the data multiple times to validate the results, to dimish the effect of the single estimation
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- Average of the $\mathbf{k}$ model error is supposed as the model error
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- Overall goal: Draw samples multiple times to underline your model (e.g. with the variance of the parameters)
- Bagging (Use Bootstrapping to improve the results) The final parameters can be achieved by averaging the $k$ sets of parameters
- We will discuss bagging and more ensemble methods in a later lecture.
- Overall goal: Draw samples multiple times to underline your model (e.g. with the variance of the parameters)
- Pseudo algorithm:
- Draw k bootstrap samples from the data
- Learn the model on each sample
- Calculate the mean and standard deviation
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- We will discuss bagging and more ensemble methods in a later lecture.
- The goal is to fulfill Occam's razor: Choose the simplest model that still explains the data.
- How do we measure the complexity of the model?
- Two ideas:
- The Minimum Description Length Principle
- Akaike's and the Bayesian Information Criterion


## The Minimum Description Length Principle

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- The quality is than measured by the number of bits needed to code these two


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- Basic Idea: Regard the routine as a way of data compression
- To recreate the data, two things are needed:
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## Example for the MDL

- We restrict the coding of the decimals to two digits reversed and ignore the sign
- Example:
- code 0.73 as 37
- 1.23 as 321
- -0.06 as 6


Table 5.7 The errors for the three regression functions

| ID | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :--- | ---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $y=1.92$ | 0.73 | 0.59 | -0.11 | 0.71 | 0.12 | -0.41 | 0.29 | -0.96 | -0.92 |
| $y=1.14+0.19 x$ | -0.05 | 0.00 | -0.51 | 0.50 | 0.10 | -0.24 | 0.65 | -0.41 | -0.18 |
| $y=1.31+0.05 x+0.02 x^{2}$ | 0.12 | 0.05 | -0.54 | 0.43 | 0.03 | -0.27 | 0.70 | -0.24 | 0.15 |

## Example for the MDL

- Coding the constant function:
- 3 digits for the value 1.92
- And for each "error" 2 digits resolves in:
- $21=3+9 * 2$


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## Example for the MDL

- Coding the linear function:
- 3 digits for the value 1.14 and 2 digits for the offset 0.19
- Error: 7 times 2 digits and for 1: 1 digit and for 2 : 0 digits
- $20=5+7 * 2+1+0$


Table 5.7 The errors for the three regression functions

| ID | $l$ | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :--- | ---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | ---: |
| $y=1.92$ | 0.73 | 0.59 | -0.11 | 0.71 | 0.12 | -0.41 | 0.29 | -0.96 | -0.92 |
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## Example for the MDL

- Coding the quadratic function:
- 3 digits for the value 1.31 and 1 digit for the raising 0.05 and 1 for 0.02
- Error: 7 times 2 digits and for ID 2 and 5 only 1 digit
- $21=5+7 * 2+2 * 1$


Table 5.7 The errors for the three regression functions

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## Example for the MDL

## Summary:

- Constant $=21$
- Linear $=20$
- Quadratic $=21$
- Recommendation would be to use the model "linear function" for this data


Table 5.7 The errors for the three regression functions

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## Other Model Selection Criteria

- Akaike's Information Criterion measures
- model complexity by number of parameters (k)
- Fit to data by probability of data generated by model (L)
- $A I C=2 k-2 \ln (L)$
- Notes:

For error assumed to be normal distributed, MSE models the likelihood directly.

- Other Measures: Bayesian information criterion.

