

High-Performance Outlier Detection Algorithm for Finding Blob-Filaments in Plasma

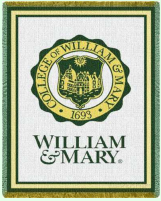
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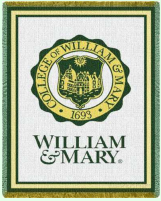
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What is an outlier ?

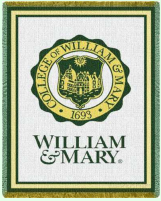
An outlier is a data object that deviates significantly from the rest of the objects, as if it were generated by a different mechanism.¹

- Outliers could be errors or noise to be eliminated
- Outliers can lead to the discovery of important information in data

Outlier detection is employed in a variety of applications:

- fraud detection
- time-series monitoring
- medical care
- public safety and security

¹ Jiawei Han and Micheline Kamber, *Data Mining, Southeast Asia Edition: Concepts and Techniques*, Morgan kaufmann, 2006.



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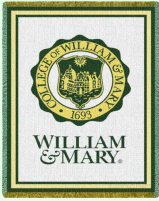
Our goal

Outlier detection is an important task in many safety critical environments.

- An outlier demands to be detected in real-time
- A suitable feedback is provided to alarm the control system
- The size of data sets need fast and scalable outlier detection methods

Our goal: apply the outlier detection techniques to effectively tackle the fusion blob detection problem on extremely large parallel machines

- Massive amounts of data are generated from fusion experiments / simulations
- Near real-time understanding of data is needed to predict performance



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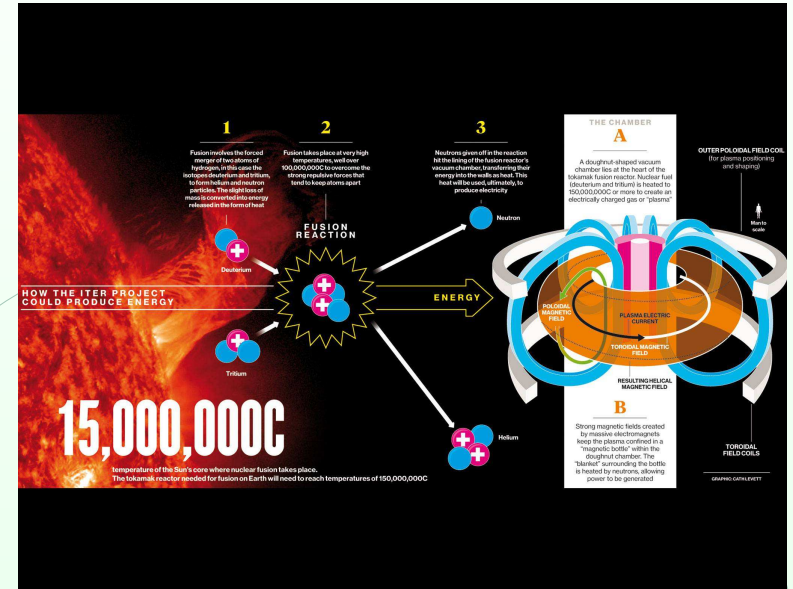
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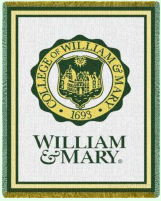
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Blobs in fusion

What is fusion & Why fusion?

- Fusion is viable energy source for the future
- Fossil fuels will run out soon; Solar and wind have limited potential
- Advantages of fusion: inexhaustible, clear and safe





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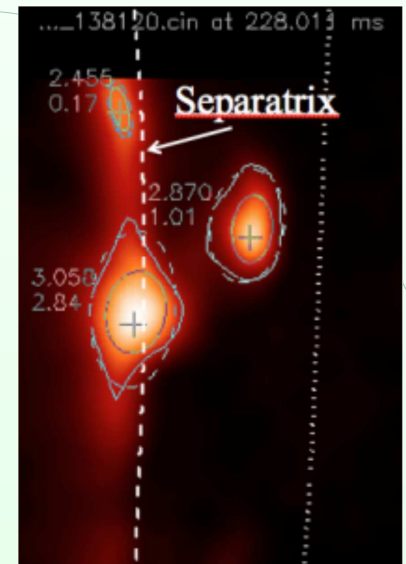
Blobs in fusion

Blobs are intermittent bursts of particles near the edge of the confined plasma

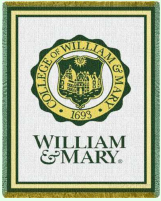
⇒ Driven by turbulence

Blobs are bad for fusion performance because they:

- Transport heat and particles away from the confined plasma
- May damage the main chamber wall
- Lead to increased levels of neutrals and impurities, bypassing control mechanisms



Blob detection is a very important task!



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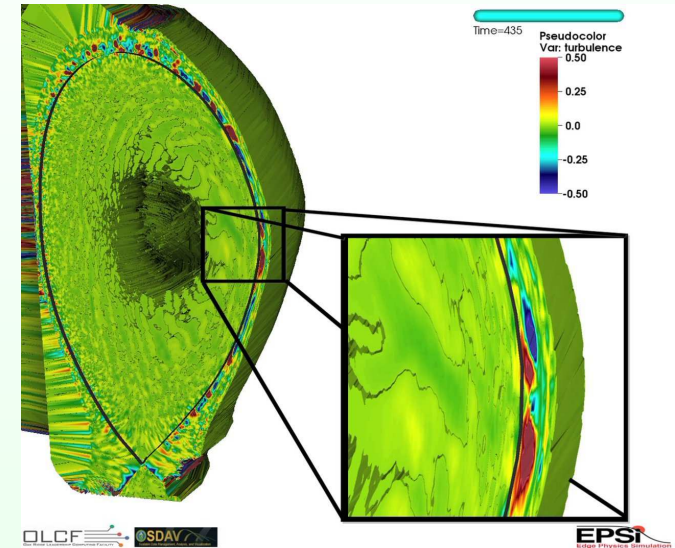
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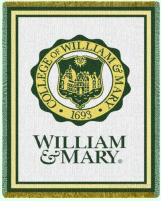
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Big data challenges in fusion energy

Fusion experiments generate massive amounts of data:

- Diagnostics measuring lasts from a few to several hundred seconds generating large amounts of data, \sim Gigabytes to Terabytes!
- Large-scale fusion simulation generates \sim a few tens of Terabytes per second!





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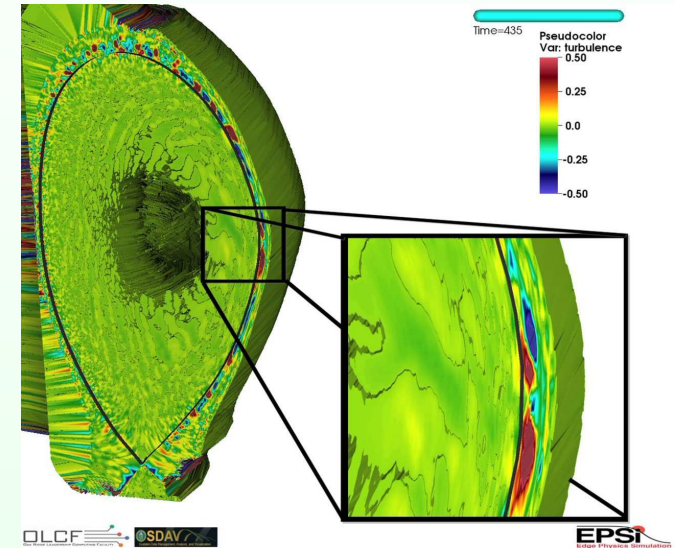
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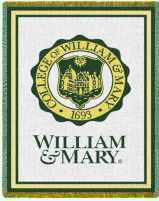
Big data challenges in fusion energy

Difficulties in large-scale data analysis:

- Existing data analysis is often a single-threaded, slow, and only for post-run analysis
- Fusion experiments demand real-time data analysis
- E.g. ICEE aims to apply blob detection for monitoring health of fusion experiments in KSTAR



Real-time blob detection is a very challenging task!



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Three approaches for blob detection

Single
threshold &
conditional
averaging

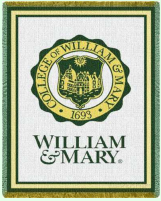
- The exact criterion varies
- Averaging may destroy important information

Image
analysis
techniques

- Very sensitive to the setting of parameters
- Hard to use generic method for all images

Contouring
method &
thresholding

- Can not be a real-time blob detection
- May miss detecting blobs at the edge
- Is still post-run-analysis



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● **Our approach**

- The sketch
- Refine mesh
- Two-step detection
- Fast CCL

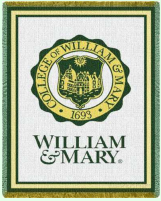
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An efficient blob detection approach

- **Our approach:** an outlier detection algorithm for efficiently finding blobs in fusion simulations / experiments
 - Two-step outlier detection with various criteria after normalizing the local intensity
 - Leverage a fast connected component labeling method to find blob components based on a refined triangular mesh
- **Contributions:**
 - A new method not missing detection of blobs in the edge of the region of interests compared to contouring method
 - Targeting for more challenging in-shot-analysis and between-shot-analysis
 - The first research work to achieve blob detection in a few milliseconds



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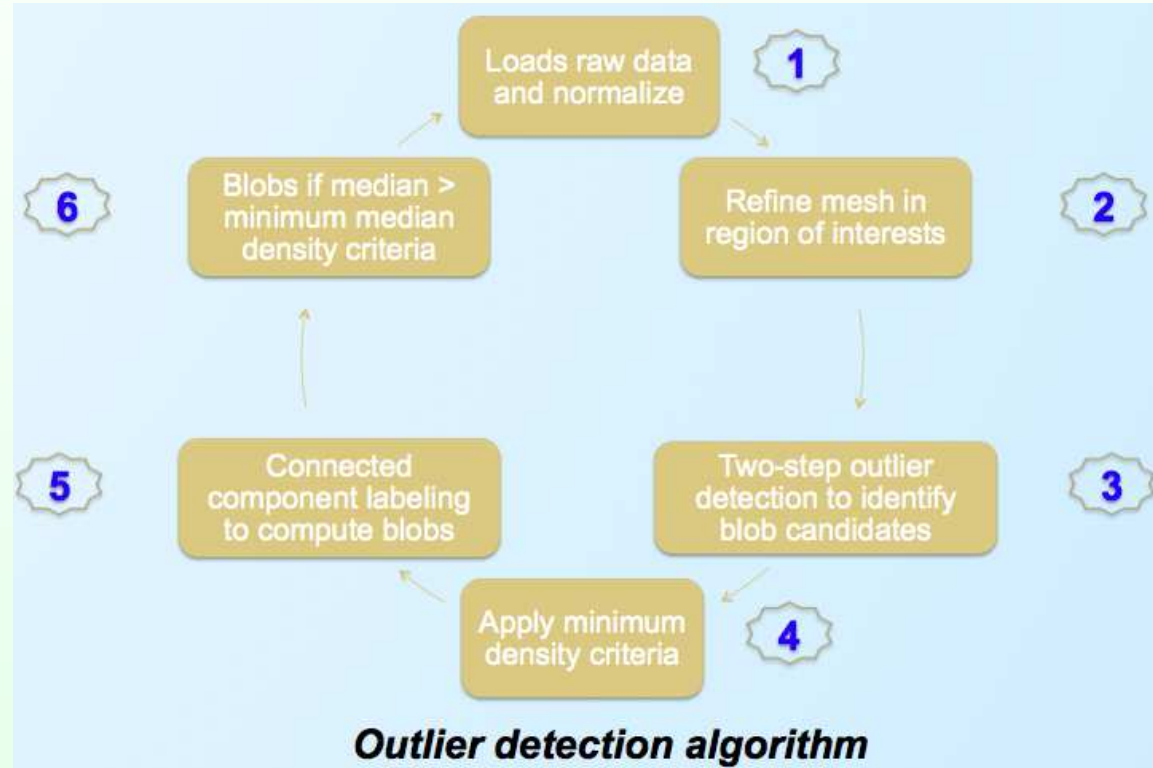
Hybrid parallel

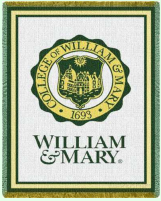
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Outlier detection algorithm for finding blobs

Sketch the proposed outlier detection algorithm:





Refine mesh in the region of interests

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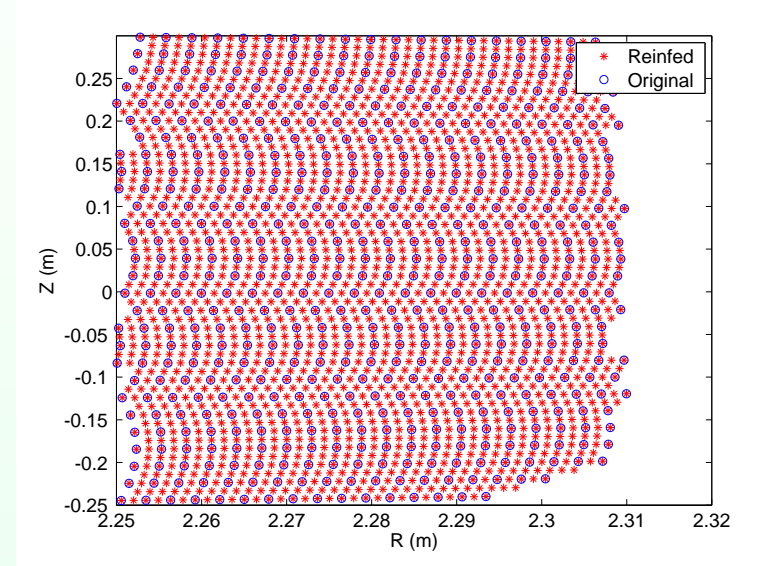
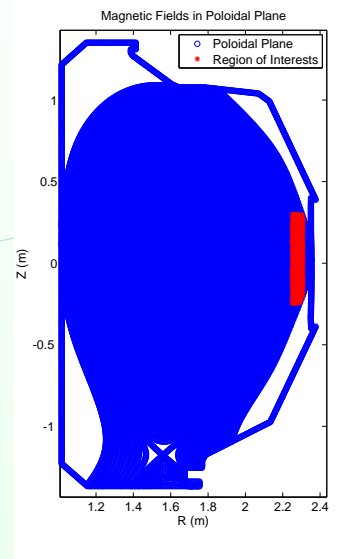
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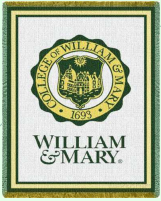
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- Compute 4 times more triangles by creating new vertexes with the three middle points of original edges
- Apply recursively until reaching the desired resolution
- Depend on specified data set and demanded resolution



Two-step outlier detection to identify blobs

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● **Two-step detection**

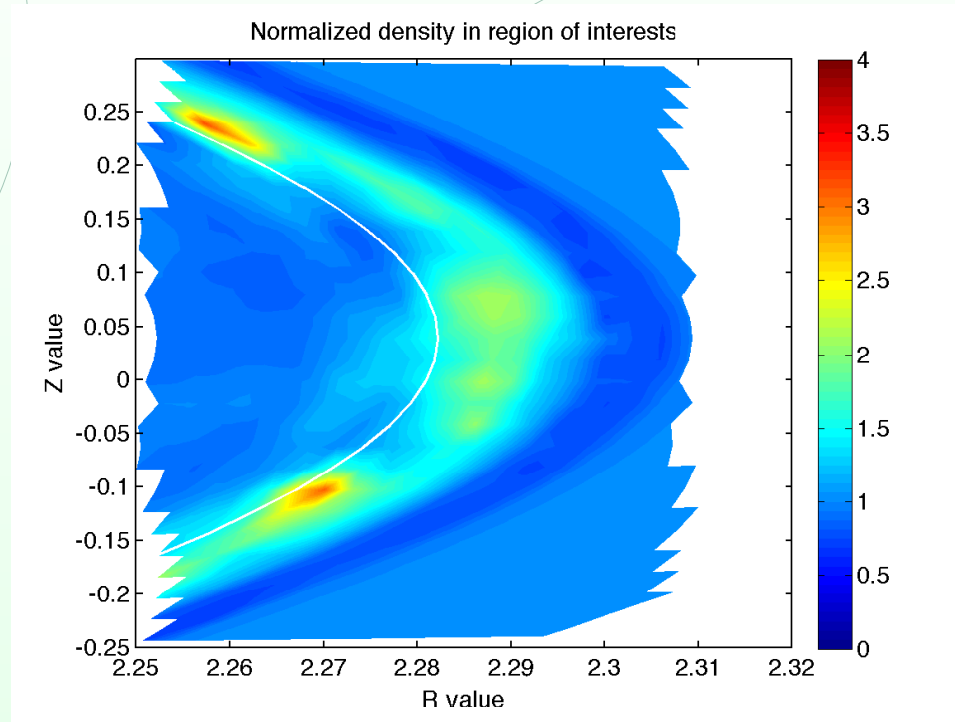
● Fast CCL

Hybrid parallel

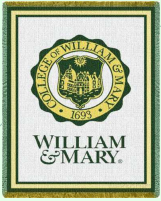
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Motivation for two-step outlier detection for finding blobs:



A contour plot in the region of interests



Two-step outlier detection to identify blobs

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● Two-step detection

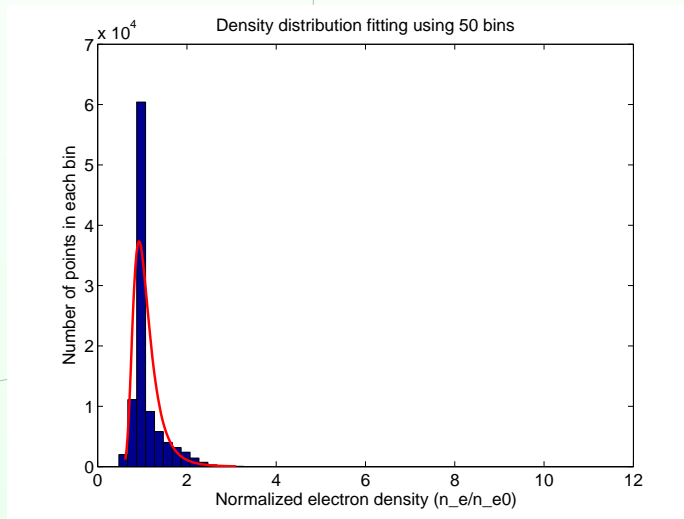
● Fast CCL

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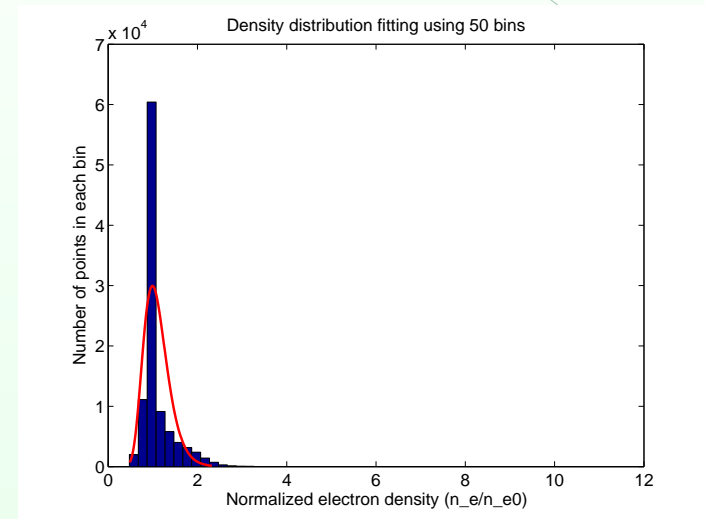
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Apply exploratory data analysis to analyze the underlying distribution of the local normalized density:

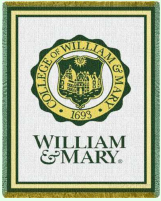


(a) Extreme Value Distribution



(b) Log Normal Distribution

$$\left[\begin{array}{l} N(r_i, z_i, t) - \mu > \alpha * \sigma, \forall (r_i, z_i) \in \Gamma, \\ N(r_i, z_i, t) - \mu_2 > \beta * \sigma_2, \forall (r_i, z_i) \in \Gamma_2. \end{array} \right]$$



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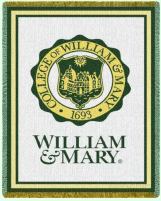
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A fast connected component labeling algorithm

We apply an efficient connected component labeling algorithm on a refined triangular mesh to find blob components:

- This is a two-pass approach and each triangle is scanned firstly
- Reduce unnecessary memory access if any vertex in a triangle is found to be connected with others
- After the label array is filled full, we need flatten the union and find tree
- Second pass is performed to correct labels and all blob candidate components are found



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● MPI/OpenMP

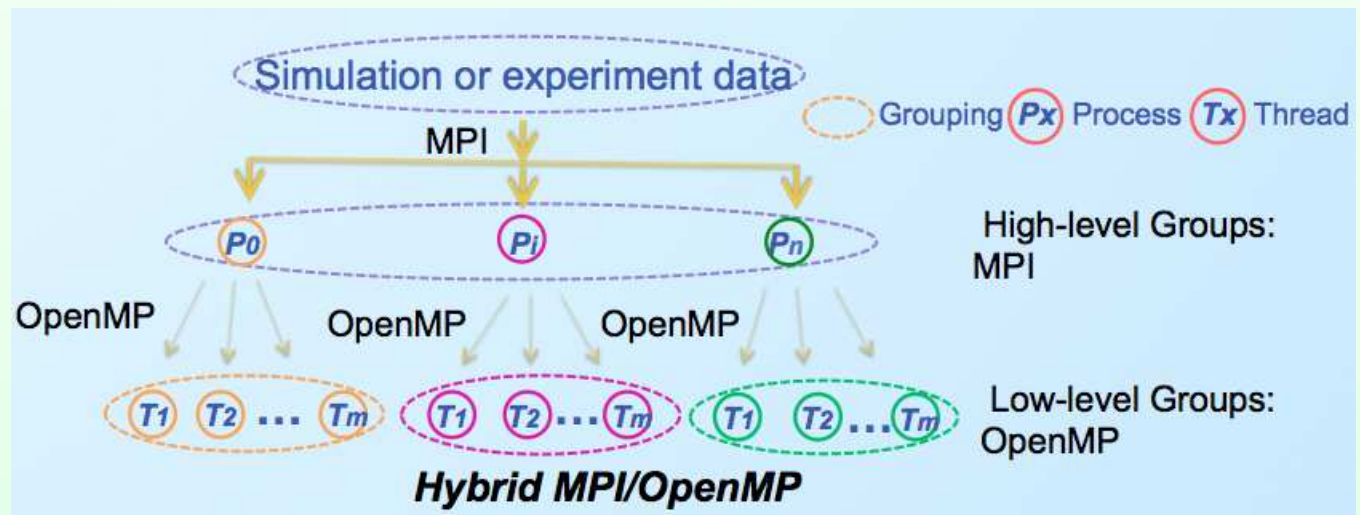
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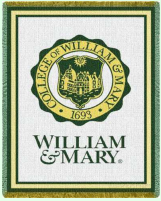
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Parallelization of blob detection approach

A hybrid MPI/OpenMP parallelization on many-core processor architecture:

- High-level: use MPI to allocate n processes to process each time frame
- Low-level: use OpenMP to accelerate the computations with m threads





Results: same time frame + four planes

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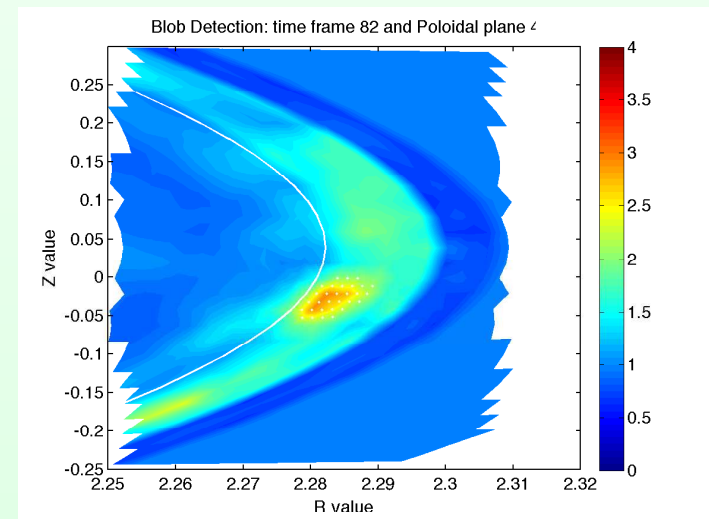
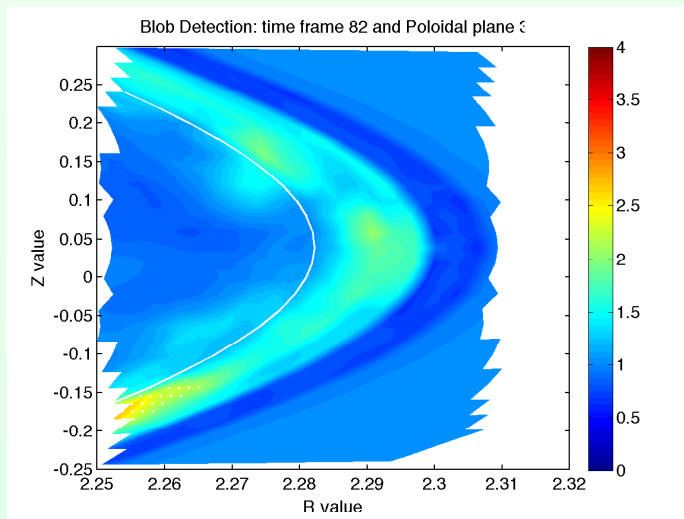
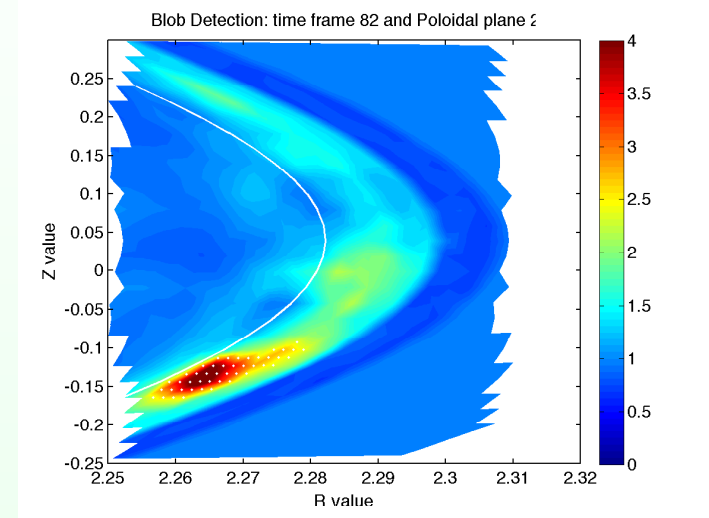
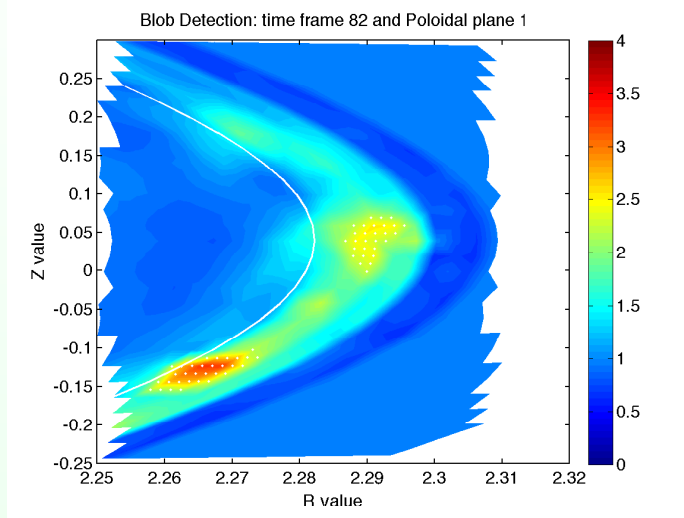
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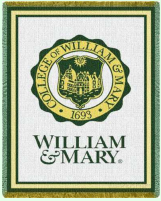
● Results I

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Results: same plane + four time frames

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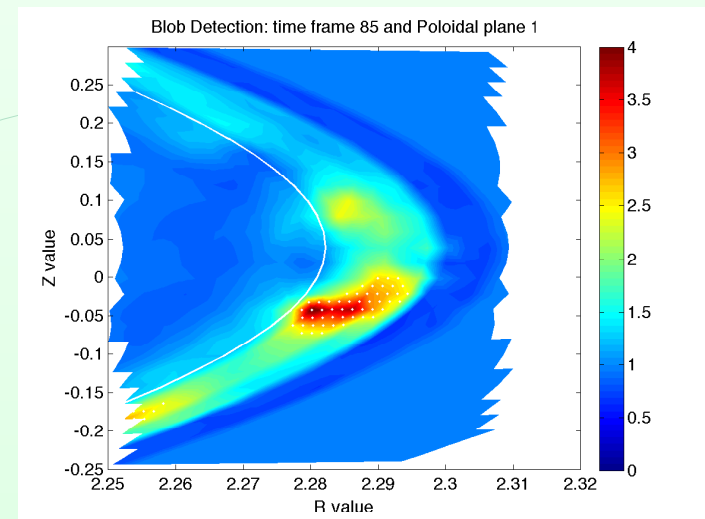
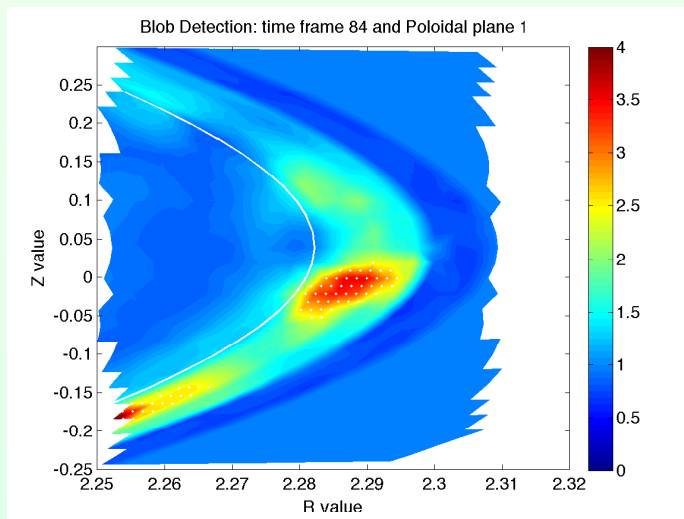
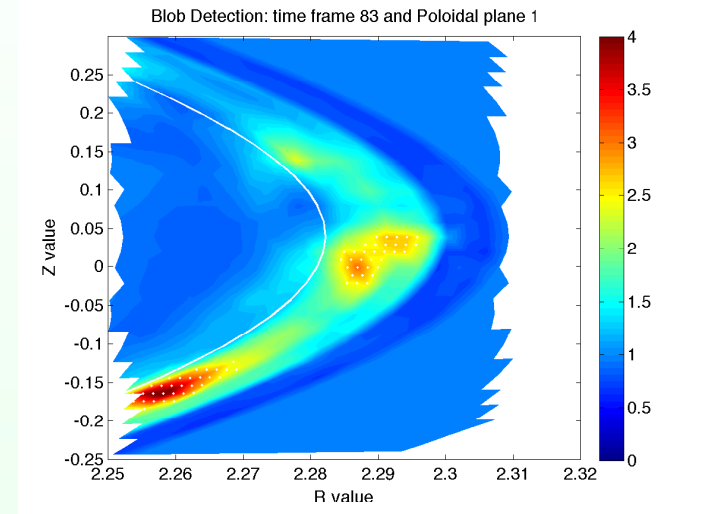
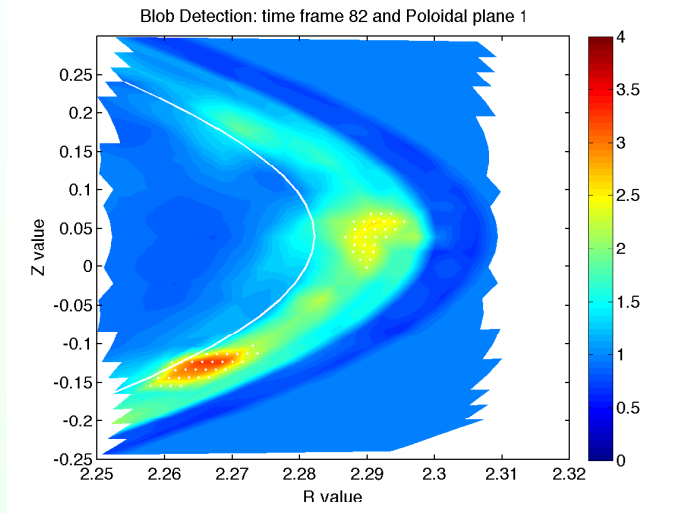
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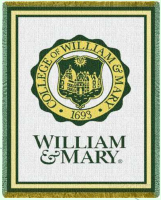
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Results: real-time blob detection

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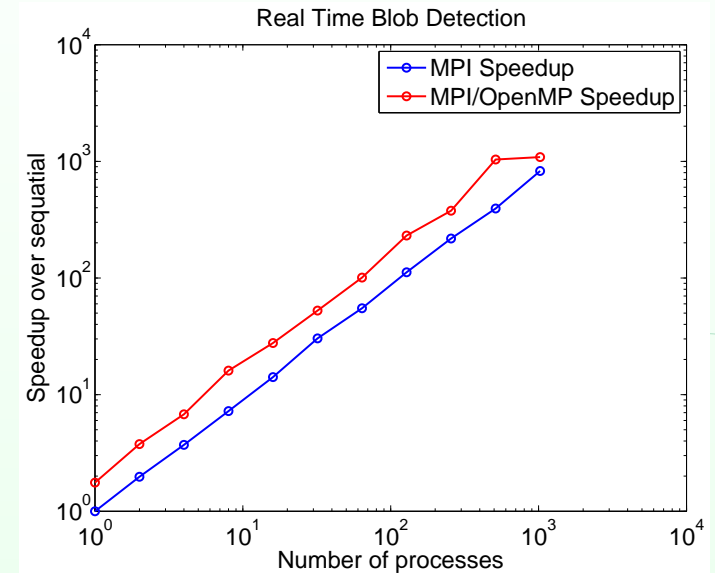
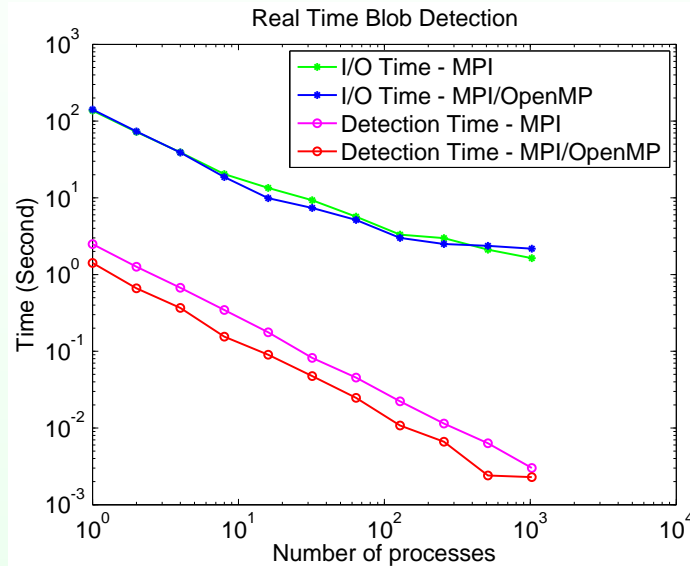
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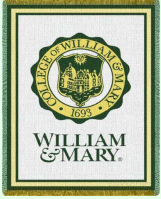
● Results II

● Results III

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- Complete blob detection in around 2 ms with MPI/OpenMP using 4096 cores and in 3 ms with MPI using 1024 cores
- MPI/OpenMP is two times faster than MPI
- Linear time speedup in blob detection time and slightly more in I/O time



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Conclusion and future work

We present for the first time a real time blob detection method for finding blob-filaments in real fusion experiments or numerical simulations.

- Key components:
 - Two-step outlier detection with various criteria
 - A fast connected component labeling method
 - Hybrid MPI/OpenMP parallelization
- Future work:
 - Test the detection algorithm to experimental measurement data from operating fusion devices
 - Develop a blob tracking algorithm