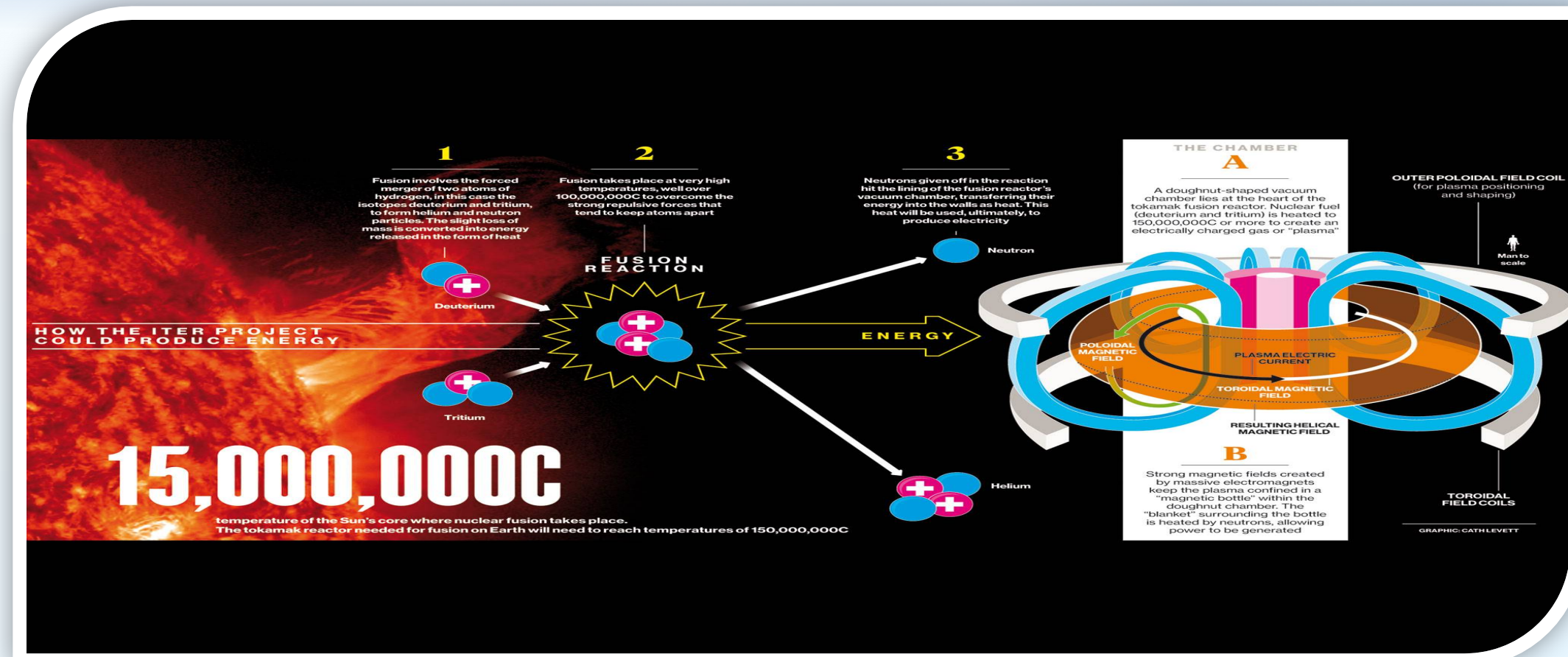


Real-Time Outlier Detection Algorithm for Finding Blob-Filaments in Plasma

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Introduction



Reprinted image from <http://www.independent.co.uk/>

Magnetic Fusion

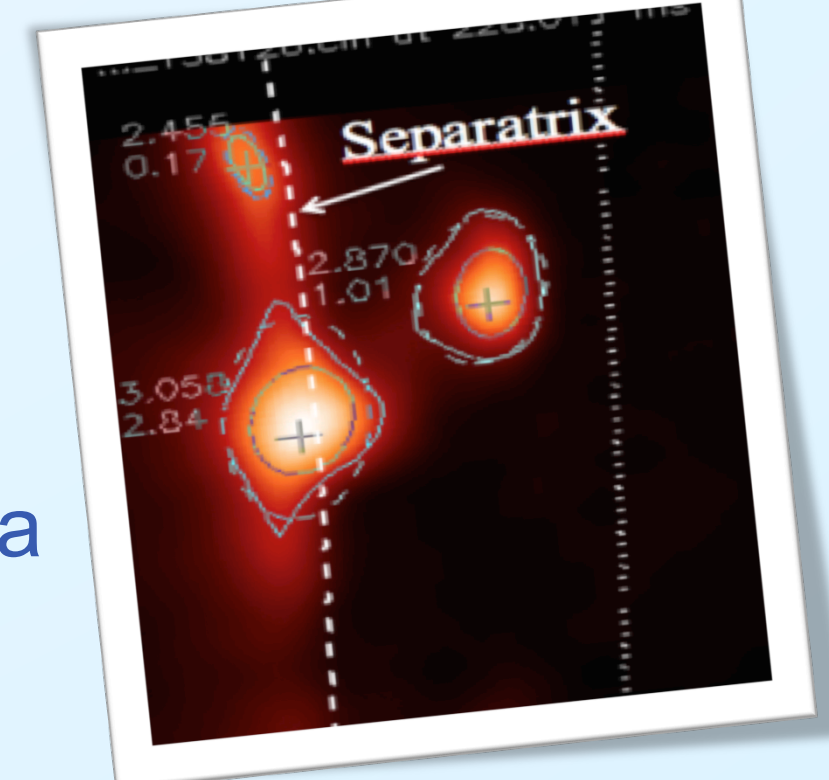
1 What is fusion & why fusion?

- ✦ Fusion is a viable energy source for the future
- ✦ Fossil fuels will run out soon; Solar and wind have limited potential
- ✦ Advantages of fusion: Inexhaustible, clean, and safe

2 Tokamak and Blobs

- ✦ Tokamak demands steady-state plasma confinement challenged by blobs
- ✦ Blobs carry high energy and plasma outside the magnetic confinement towards the wall
- ✦ Blobs result in loss of heat, degrading plasma confinement and erosion of the wall.

Reprinted image from <http://why-sci.com/edge-turbulence-and-blobs-could-smaller-be-better/>



★ **Blob detection is a very important task!**

Motivation

✦ Fusion experiments generate massive data

- ✦ Three types of analysis: In-shot-analysis, between-shot-analysis, and post-run-analysis
- ✦ A shot lasts from a few seconds to several hundred seconds, generating ~ a few Gigabytes to a few Terabytes data sets !
- ✦ Large-scale simulation generates ~ 15 Terabytes per second !

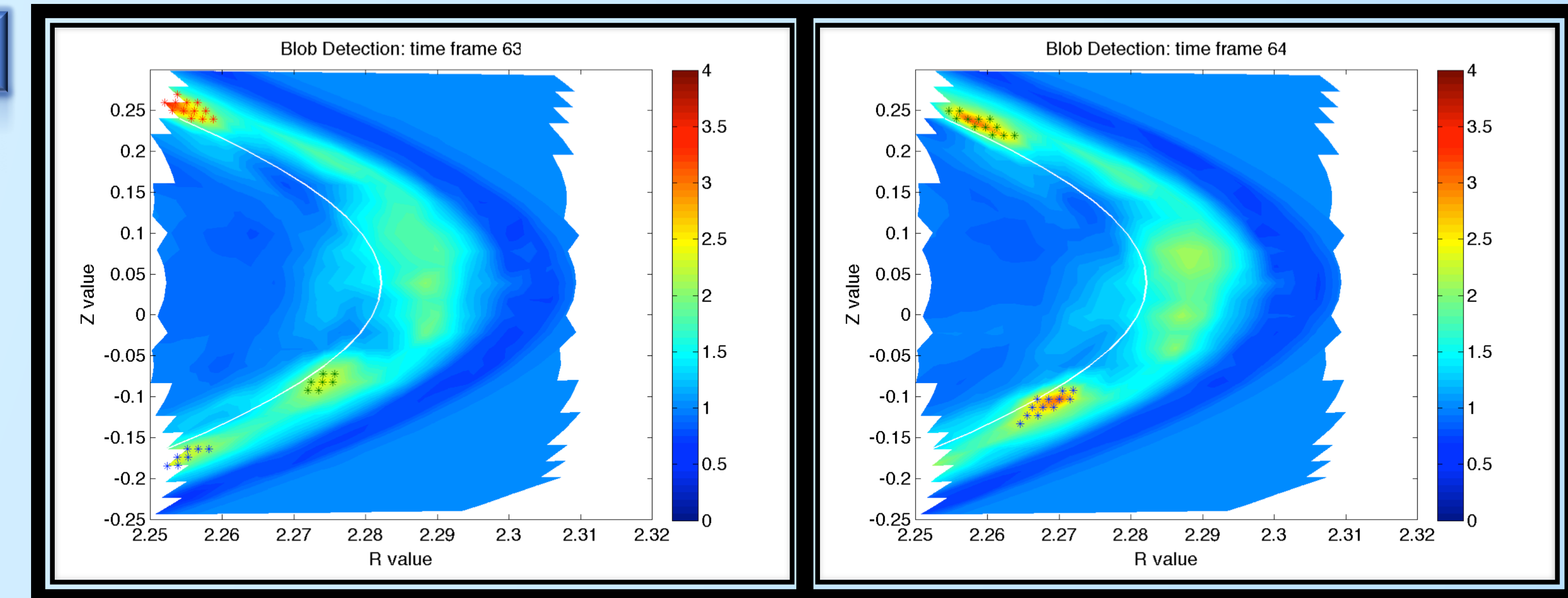
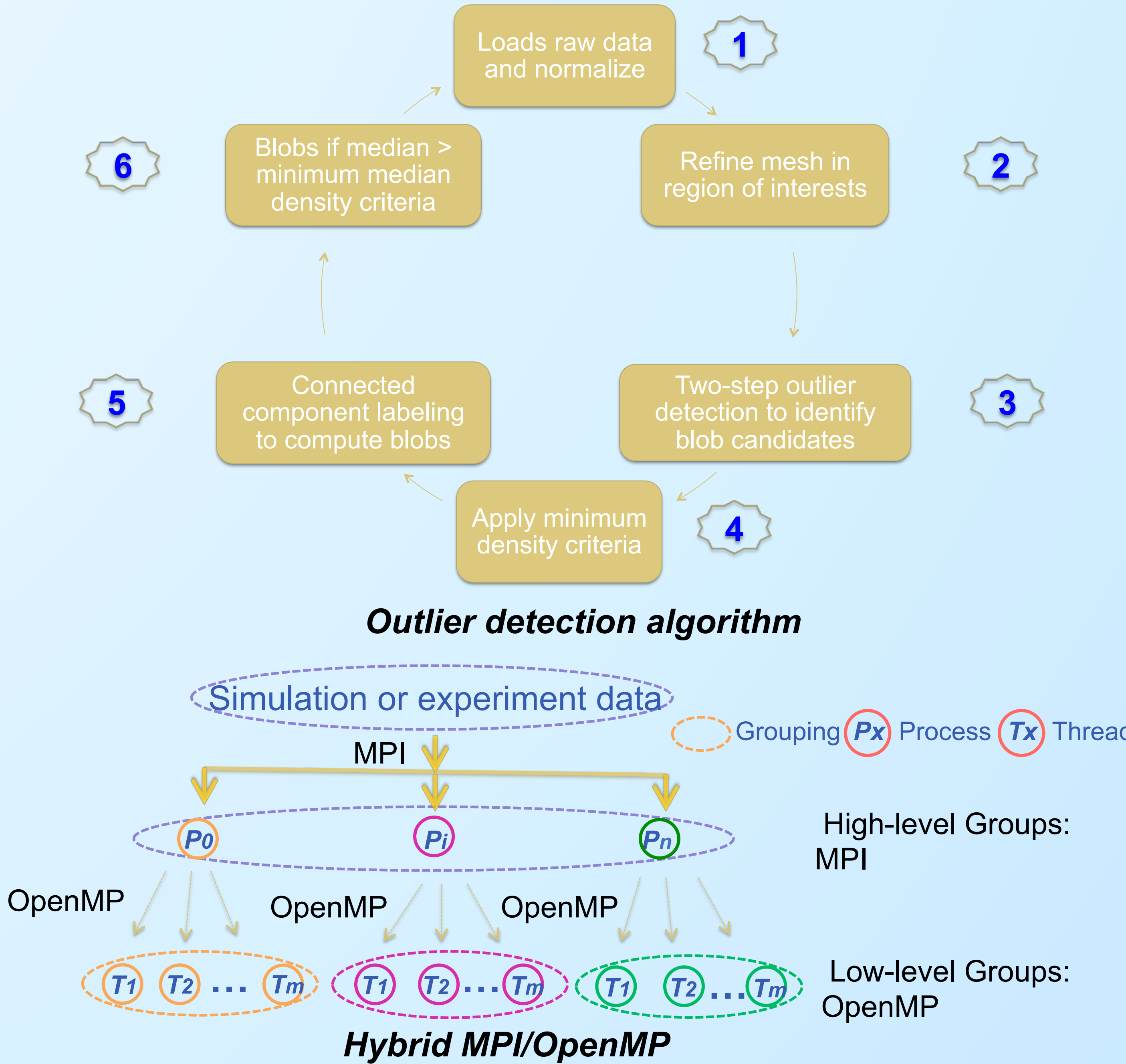
✦ Difficulty in large-scale data analysis

- ✦ Existing data analysis approaches are often a single-threaded, only for post-run analysis and take a long time to produce results
- ✦ Real fusion experiments demand real-time data analysis
- ✦ Example: ICEE, developed by researchers in ORNL, LBNL and PPPL, builds an in transit data processing framework for near real-time scientific applications. It aims to provide safety critical functions (such as blob detection) in KSTAR to monitor health of fusion experiments.

★ **Real-time blob detection is a very challenging task!**

An Efficient Blob Detection Approach

✦ **Our approach:** develop a real-time outlier detection algorithm for efficiently finding blobs in numerical simulations and fusion experiments



Example blob in two continuous time frames

✦ Outline of the new blob detection algorithm:

- 1 Loads raw simulation or experimental data in each time frame and computes normalized density
- 2 Refine the triangular mesh in the region of interests
- 3 Apply two-step outlier detection to identify blob candidates with appropriately chosen confidence level in the region of interests
- 4 Compare the normalized density of blob candidates with the minimum density criteria to filter out unwanted candidates
- 5 Apply connected component labeling to compute different blobs
- 6 A blob is found if its median satisfies minimum median density criteria

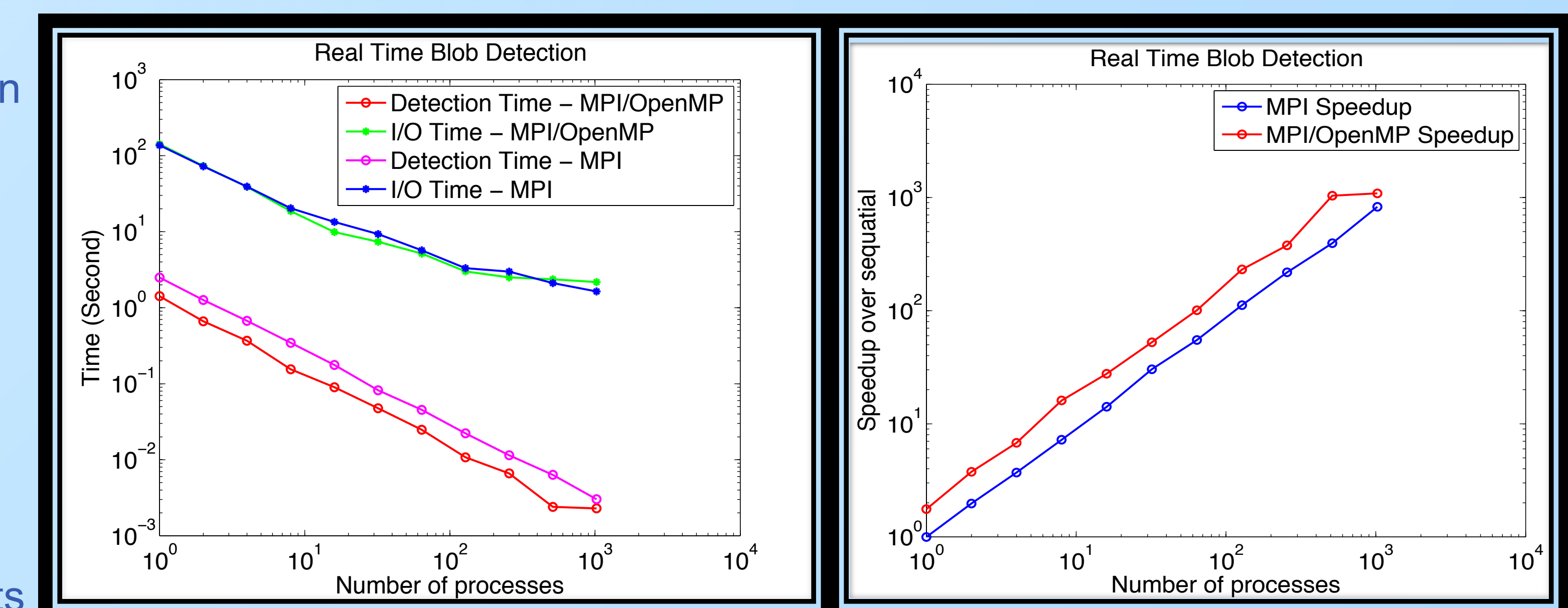
✦ A real-time blob detection approach using hybrid MPI/OpenMP:

- 1 High-level: use MPI to allocate n processes to process each time frame
- 2 Low-level: use OpenMP to accelerate the computations with m threads

Preliminary Results

✦ Results:

- ✦ We implement the proposed algorithm in C and test our implementation on NERSC supercomputer Edison with MPI and OpenMP
- ✦ Our data sets (33GB) is from the XGC1 simulation containing 1024 time frames which last around 2.5 milliseconds (ms)
- ✦ **Most Encouraging results:** complete blob detection in around **2 ms** with MPI/OpenMP using 4096 cores and in **3 ms** with MPI using 1024 cores
- ✦ MPI/OpenMP implementation is two times faster than MPI implementation
- ✦ Linear time scalability in blob detection time and slightly more in I/O time
- ✦ MPI and MPI/OpenMP achieve speedup over serial up to 800x and 1200x
- ✦ We are integrating it into ICEE and plan to test it in the KSTAR experiments
- ✦ We also plan to develop a blob tracking algorithm based on this work.



Blob detection performance

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