

Enhancing Data Availability in Disk Drives through Background Activities*

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Abstract

Latent sector errors in disk drives affect only a few data sectors. They occur silently and are detected only when the affected area is accessed again. If a latent error is detected while the storage system is operating under reduced redundancy, i.e., during a RAID rebuild, then data loss may occur. Various features such as scrubbing and intra-disk data redundancy are proposed to detect and/or recover from latent errors and avoid data loss. While such features enhance data availability in the storage system, their execution may cause performance degradation. In this paper, we evaluate the effectiveness of scrubbing and intra-disk data redundancy in improving data availability while the overall goal is to maintain user performance within predefined bounds. We show that by treating them as low priority background activities and scheduling them efficiently during idle times, these features remain performance-wise transparent to the storage system user while still improving data reliability. Detailed trace-driven simulations show that the Mean Time To Data Loss (MTTDL) improves by up to 5 orders of magnitude if these features are implemented independently. By scheduling concurrently both scrubbing and intra-disk parity updates during idle times in disk drives, MTTDL improves by as much as 8 orders of magnitude.

1 Introduction

As digital storage of commercial data and of data for strictly personal use becomes mainstream, high data availability and reliability become imminently critical. Consequently, there are substantial efforts on designing reliable disk-based storage systems by adding redundancy. Data redundancy is traditionally provided using parity locally in the form of disk arrays (e.g., RAID) [16], but distributed

storage schemes at a broader scale (e.g., the Google File System [7]) enjoy popularity.

Data redundancy protects against entire disk failures as well as failures of disk sectors. Commonly, disk sector errors are known as “latent sector errors”, because they occur silently and are detected only when the affected area on the disk is accessed again [1, 2, 6, 11, 20]. While latent sector errors may be detected when the user tries to access the affected data, it is probable that they are detected during the data rebuild process, because data rebuild accesses the entire disk space in order to restore the redundancy in a system with disk failure(s).

If the storage array is designed to protect from one failure only, such as RAID 1 through 5, any latent sector error detected during the data rebuild process causes data loss because there is no data redundancy to protect against the error. Storage systems with two redundancy levels, such as RAID 6 [13] are better protected and may experience data loss because of latent sector errors only if they are detected while two simultaneous failures exist in the array (i.e., a very unlikely event).

To avoid data loss because of latent errors detected during data rebuilds, features exist in the storage system that aim at detecting and recovering from latent sector errors while there is redundancy in the system. Disk *scrubbing* is an error detection technique that detects latent sector errors via background media scans [19]. *Intra-disk data redundancy* is an error recovery technique that adds another level of redundancy in the data by adding parity for sets (segments) of sectors within the same disk [3, 11].

Scrubbing could cause delays to the foreground work because disk operations such as seeks are not preemptive. Furthermore, multiple redundancy levels and intra-disk parity do impose additional work in the storage system when data is modified (e.g., during WRITE operations), because the parity must be updated. Consequently, both scrubbing and intra-disk parity updates should operate as system background processes. If the execution of this additional work competes with regular user traffic, then it may cause unde-

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In this paper, we evaluate the effectiveness of scrubbing and intra-disk data redundancy, when these techniques are designed to remain transparent to the storage system user, i.e., keep average user performance degradation within pre-defined targets. For this, we treat both these features as strictly background ones, and schedule them using effective idle time management policies [14]. Throughout our evaluation, we show that our idle time scheduling approach [14], is key to achieving the efficient execution of scrubbing and in particular of the parity updates associated with the intra-disk data redundancy feature.

Detailed trace-driven simulations indicate that, it is possible to effectively detect and recover from latent disk errors even when the system imposes strict limitations on performance degradation of user traffic. The simulation results show that background activities dramatically improve system reliability by achieving several orders of magnitude improvement of its mean time to data loss (MTTDL). Specifically, scrubbing improves the MTTDL by as much as 5 orders of magnitude, while the intra-disk data redundancy scheme evaluated improves the MTTDL by 2 orders of magnitude. We further show that running both scrubbing and intra-disk parity concurrently, utilizes best the entire system. The combination of both features results in significant MTTDL improvements, i.e., as high as 8 orders of magnitude.

This paper is organized as follows. Section 2 presents related work. Section 3 describes background material on modeling of mean time to data lost in storage system. Section 4 describes how to effectively schedule work during idle times in disk drives by taking advantage of the stochastic characteristics of the empirical distribution of disk idle times. Section 5 presents the disk level traces used in our evaluation. Analysis of scrubbing that utilizes idle times is presented in Section 6. Section 7 analyzes background-based intra-disk parity updates. In Section 8 we evaluate performance and data reliability consequences if scrubbing and intra-disk parity updates are simultaneously enabled as background jobs. Conclusions are given in Section 9.

2 Related Work

The metric of interest when it comes to storage system reliability is not the traditional Mean-Time-To-Failure (MTTF) [18], but instead the Mean-Time-To-Data-Loss (MTTDL) [2]. Data loss is caused when additional failures (even of a few data sectors) occur or are detected in a system which has lost its redundancy because of previous failures. While simultaneous failures of multiple disks are rare, disk sector errors may be detected during a data rebuild, i.e., when the system has lost its redundancy, and cause data loss [2].

To avoid data loss, storage systems may be designed with multiple redundancy levels, i.e., RAID 6 [13]. In addition to such solutions, system features such as scrubbing [19] and intra-disk data redundancy [3, 11] represent effective ways to detect and recover from latent sector errors. Recent data show that scrubbing detects as much as 60% of all latent sector errors [1]. These features are preventive in nature but unavoidably introduce more work in the storage system and in the individual disks. To avoid penalizing regular user traffic, any additional work to enhance reliability is completed as a background process during disk or storage system idle times, which is shown to be available in storage systems [8, 17].

While a myriad of approaches have been proposed to best utilize idle times in order to enhance system performance, reliability, and consistency by exploiting it locally (i.e., within the same system) [10] or remotely (i.e., busy systems may offload part of their work in idle ones) [12], there has been a number of studies that focus solely on how to better manage idle times for scheduling background activities [5, 14]. Methods to adaptively determine how to best exploit disk idle times to schedule long, high-penalty background jobs, such as powering or spinning-down disks, can be found in [4, 9]. On the analytic side, several models have been developed for systems where foreground/background jobs coexist [21].

In this paper, we use the concept of managing idle times proposed in [14], where decision on when to start scheduling a background job is determined by the empirical distribution of the previously monitored idle times. While the study in [14] focuses on the general concept of how to utilize idle times such that the effect on foreground performance is contained within pre-defined bounds, here we focus on customizing these general background job scheduling policies for the specific case of treating scrubbing and intra-disk parity updates as background activities to enhance system reliability. We further study how to best utilize idle times to meet the different needs of an infinite activity such as scrubbing versus a finite one that depends on the specific workload such as intra-disk parity updates, and show dramatic improvements in the mean time to data loss in systems where both features are enabled.

3 Background - MTTDL Estimation

An important reliability metric for storage systems is the Mean-Time-To-Data-Loss (MTTDL). Approximate models for MTTDL as a function of various system parameters are given in [2]. Here, we calculate MTTDL with scrubbing and intra-disk data redundancy using the same models as in [2]. We first provide a quick overview of the MTTDL models presented in [2]. MTTDL is defined based on the following parameters:

- MV, ML : mean interarrival time of visible and latent disk errors, respectively,
- MRV, MRL : mean recovery time from visible and latent errors, respectively,
- MDL : mean detection time of latent sector errors,
- α : temporal locality of errors,
- β_{XY} : spatial locality of errors, where consecutive errors X and Y are either visible (i.e., type V) or latent (i.e., type L).

If no scrubbing is initiated, then MTTDL is given by the following equation:

$$\frac{1}{MTTDL} \approx \frac{\beta_{VV}}{\alpha} \frac{MRV}{MV^2} + \frac{\beta_{LV}}{\alpha} \frac{MRV}{MV \cdot ML} + \frac{1}{ML}. \quad (1)$$

If scrubbing is performed, then the above equation accounts for the average time it takes to detect the error via scrubbing (i.e., MDL) and recover from it (i.e., MRL) as follows:

$$\frac{1}{MTTDL} \approx \frac{\beta_{VV}}{\alpha k^2} \frac{MRV}{ML^2} + \frac{\beta_{LV}}{\alpha k} \frac{MRV}{ML^2} + \frac{\beta_{VL} + k\beta_{LL}}{\alpha k} \cdot \frac{MDL + MRL}{ML^2} \quad (2)$$

where $k = ML/MV$ [2]. The parameter values for Equations (1) and (2) used in the following sections of this paper are given in Table 1 and are those used in [2].

MV	ML	MRV
120,000 hrs	84,972 hrs	1.4 hrs
k	$\alpha, \beta_{VV}, \beta_{LV}, \beta_{VL}$	β_{LL}
1.41	1	0

Table 1. Parameters used for MTTDL estimation.

4 Scheduling Background Activities

Using disk idle times as a separate resource to complete background activities with minimum obstruction to foreground jobs has been the focus of scheduling policies for foreground/background jobs. *Idle waiting* [5] (i.e., delaying scheduling background jobs during idle intervals) is an effective mechanism to reduce foreground performance degradation due to non-preemptive background jobs. An algorithmic approach to estimate how long to idle wait based on the variability of observed idle periods in the system is proposed in [14], where extensive experimentation shows that the efficiency of idle waiting increases as variability of the empirical distribution of idle times increases¹.

Idle waiting combined with an estimation of the number of background jobs to be served within an idle interval, allows meeting foreground performance requirements

¹For more details, we refer readers to the technical report [15].

while serving as many background jobs as possible. The statistical characteristics of idle times can assist in defining how long to idle wait before scheduling background jobs. In [14], the empirical distribution function of idle times is used to determine the length of “idle wait” in the following three background scheduling policies:

body-based: If the variability of idle times is low, then idle wait for a short period. This policy schedules a *few* background jobs in most idle intervals, which results in using the body rather than the tail of the idle times empirical distribution for serving background activities.

tail-based: If the variability of idle times is high, then idle wait for a long period. This policy schedules *many* background jobs in a few idle intervals by using the tail rather than the body of the idle times empirical distribution for serving background activities.

tail+bursty: If burstiness exists in idle times, then it is possible to obtain more accurate prediction about upcoming idle intervals because long idle intervals are “batched” together. After a long idle interval is observed, then it is possible to predict with good accuracy if the next interval is also long, which then allows for more effective scheduling of background activities.

The goal of the body-based policy is to use most of the idle periods in the system and schedule only few background jobs in an idle period. This policy works particularly well for cases with low variability in idle times because all idle intervals are of similar length. In contrast, for idle intervals of high variabilities, the idle waiting time in the tail-based and the tail+bursty policies is much longer, avoiding utilization of most idle periods which results in delaying only few foreground jobs. Although the tail-based policies utilize only few long intervals, the total amount of background work scheduled during those long intervals is yet more when compared to the background work scheduled under the body-based policy. Tail-based policies are effective only if the idle times are highly variable, which implies that very long idle periods are *expected* to eventually occur. In the following sections, we elaborate on how the above policies can be used in the context of scrubbing and intra-disk parity updates to increase MTTDL.

5 Trace Characteristics and Simulation

All policies presented here are evaluated via trace driven simulations, see [17] for a detailed description of the statistical characteristics of the disk drive traces. The selected three disk traces are measured in a personal video recording device (PVR), a software development server, and an e-mail

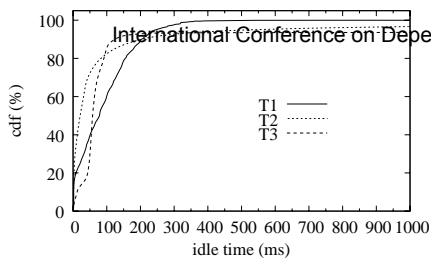


Figure 1. CDF of idle times for traces T1, T2 and T3.

server, which we refer throughout the paper by T1, T2, and T3, respectively. Table 2 gives a summary of the overall characteristics such as request mean interarrival time, request mean service time, utilization, as well as the mean and the coefficient of variation (CV) of idle intervals in the trace. Traces T1, T2 and T3 have 427K, 500K and 362K entries, respectively. They differ from each other in the stochastic characteristics of their idle intervals. For trace T1, idle intervals have a CV close to one, while traces T2 and T3 have higher variability with CVs as high as 6.41 and 3.79, respectively. Consequently, traces T2 and T3 have longer tails than trace T1, see Figure 1. Furthermore, the time series of the observed idle intervals for traces T1 and T2 are not bursty, while the time series of idle intervals for trace T3 is bursty.

Trace	Mean Arrival	Mean Service (ms)	Util (%)	Mean Idle (ms)	CV Idle	Bursty
T1	62.85	10.68	17	91.98	0.98	No
T2	96.72	4.20	4.2	236.08	6.41	No
T3	252.29	5.59	2.2	760.84	3.79	Yes

Table 2. Overall characteristics of traces.

The focus here is on the evaluation of scrubbing and parity updates related to intra-disk data redundancy as background activities. Scrubbing is an *infinite* background process because commonly upon completion of one entire disk scan, a new one starts. Parity updates depend on the WRITE user traffic and are considered a *finite* background process. The specific parameters of scrubbing and intra-disk parity update used in our simulations are as follows.

Scrubbing is abstracted as a long background job that is preemptive at the level of a single disk request. Hence, it is assumed that an entire scan of a 40GB disk, i.e., one complete scrubbing, requires 100,000 disk IOs, each scanning approximately 1000 sectors. Disk capacities of 40GB might be conservative given that modern disk drives reach capacities of up to 500GB, but we stress that the analysis presented here is independent of the disk size. One single disk scan request as part of the scrubbing job is assumed to take on the average as much time as a READ disk request. In our simulations, this time is drawn from an exponential distribution with mean 6.0 ms. The time to serve 100,000

disk IOs as part of a single scrubbing corresponds the average scrubbing time.

Parity updates are abstracted as short background jobs. To update the parity of a segment of sectors, the following steps are taken. First, the entire set of sectors should be read, then the parity must be calculated, and finally the new parity is written on the disk. Therefore, each parity update consists of one READ (assumed to take 10 ms on the average) and one WRITE (assumed to take 5 ms on the average), both exponentially distributed. The preemption level of parity updates is at the disk request level. If a parity update is preempted after the READ, then the system maintains no memory of the work done and the update has to restart during another idle period. Parity updates are served in a first-come-first-served (FCFS) fashion.

Scrubbing and intra-disk parity updates processes are scheduled using the three policies outlined in Section 4. In storage systems, a slowdown of the foreground traffic by 5% to 10% is considered transparent to the user. Hence, we set the pre-defined limit on performance degradation to 7%. All three policies degrade the performance of user traffic by restricting the amount of background jobs served. Their efficiency regarding the performance of timely completion of background tasks (i.e., scrubbing or parity updates) depends on the variability of idle times in traces T1, T2, and T3.

6 Disk Scrubbing

Background media scans can be abstracted as an *infinite* background process that detects any possible media errors on disk drives and thus prevents data loss caused by latent sector errors. As a preventive feature, scrubbing is completed in the background and can be conducted by the storage system or the disk drive itself. Based on the system specifications described in Section 5, we evaluate the effectiveness of scrubbing aiming at degrading performance of user traffic by at most 7%.

The goal of scrubbing as a preventive background feature is to improve the MTTDL. The average time of scrubbing allows for MTTDL calculation when scrubbing is not running and when it is running, using Equations (1) and (2), respectively. The mean detection time of sector errors (MDL) in Equation (2) is set to be equal to $0.5 \times$ average scrubbing time. Moreover, compared to detection times, the recovery times of latent sector errors are insignificant (i.e., $MRL \ll MDL$). We thus assume $MRL \approx 0$ in Equation (2). Table 3 gives the improvements in MTTDL when scrubbing is running over the case when it is not running, i.e., the ratio of the two MTTDLs. The results show that when utilizing the body and the tail of idle times as explained in Section 4, scrubbing dramatically improves reliability while the degradation in the performance of user traffic is limited to 7%. The overall improvement of MTTDL

because of scrubbing is 5 orders of magnitude. Differences in the MTTDL improvement between the scheduling policies are between 20% and 40%. The body-based policy achieves better MTTDL improvement for low variable idle times (e.g., trace T1) than the tail-based policy. For T2 that has high variability in idle times, the tail-based policy is superior to the body-based policy. Additionally, the prediction of upcoming idle times further improves the system's reliability for trace T3 whose idle times are bursty.

T1		T2		T3	
body	tail	body	tail	tail	tail+bursty
0.4 $\times 10^5$	0.3 $\times 10^5$	0.3 $\times 10^5$	0.5 $\times 10^5$	0.4 $\times 10^5$	0.5 $\times 10^5$

Table 3. MTTDL improvement via scrubbing.

Table 4 also provides an explanation for the differences in the MTTDL improvement between the three scheduling policies by presenting the number of completed media scans, their average scrubbing time, and the overall system utilization. For lowly variable idle times (e.g., T1), utilizing the body rather than the tail of idle times results in faster scrubbing and better overall system utilization. In particular, scrubbing under the body-based policy is twice faster than under the tail-based policy (see first row of Table 4). Consequently, the faster scrubbing time under the body-based policy yields the superior MTTDL improvements shown in Table 3. For T2 that has highly variable idle times, the tail-based yields faster scrubbing, i.e., at least two orders of magnitude difference than the body-based policy, which results in higher MTTDL improvement. Furthermore, for trace T2, the system is a lot better utilized under the tail-based policy. Finally, if idle times are in addition bursty (i.e., trace T3), then utilizing the tail of idle times and predicting long idle periods performs better than utilizing only the tail of idle times. Utilizing burstiness to benefit scrubbing results in a five-fold improvement in mean scrubbing time. The body-based policy is not evaluated for T3 because the results of T2 establish that the tail rather than the body of idle times should be used if idle times have high variation.

In addition to the average performance presented in Table 4, we also evaluate the distribution of scrubbing time. The distribution is built with a sample space of completed scrubbing as large as 500 by replaying the traces several times. Figure 2 shows the cumulative distribution function (CDF) of scrubbing time for traces T1, T2, and T3. For all three traces, the best performing scheduling policy for scrubbing identified in Table 4 achieves the shortest scrubbing distribution tail. For trace T1, see Figure 2(a), almost 100% of scrubblings have times less than 3831.9 seconds under the body-based policy while a twice larger scrubbing time is achieved for only 1.4% of scrubblings under the tail-

Trace	Policy	Completed Media Scans	Mean Scrubbing Time (s)	System Util (%)
T1	body	6	3,617.8	33.1
	tail	4	6,484.7	26.8
T2	body	4	11,519.6	9.7
	tail	63	726.4	83.1
T3	tail	20	4,476.3	14.3
	tail+bursty	94	972.9	62.6

Table 4. Scrubbing performance for traces T1, T2, and T3 under body-based, tail-based, and tail+bursty idle time managing policies.

based policy. Similarly for trace T2, see Figure 2(b), the tail of scrubbing time under the tail-based policy is about 7.5 times shorter than under the body-based policy. Exploiting burstiness with the tail+bursty policy, as shown in Figure 2(c), further reduces the tail of the scrubbing time distribution.

7 Intra-disk Parity Updates

Intra-disk data redundancy requires maintaining updated parity that becomes dirty if the corresponding data is modified [3, 11]. This extra amount of work required to maintain updated parity consists of an extra READ and an extra WRITE for each user-issued WRITE. Completing this work instantaneously upon completion of each user-issued WRITE is called *instantaneous parity* (IP) update. Naturally, IP causes degradation in user performance because it is not a preemptable task, but provides the highest level of data reliability.

Here, we show that it is possible to complete parity updates as a background job in a timely fashion, while keeping user performance slowdown within the predefined target 7%. We quantify how the amount of delay in intra-disk parity updates affects data reliability for the three idle scheduling techniques. The effectiveness of the idle scheduling policies are evaluated in comparison to IP updates.

7.1 MTTDL in Data Redundant Drives

The estimation of MTTDL for disks with intra disk redundancy is based on Equation (1). Assuming that latent sector errors are spatially and temporally correlated [1], the improvement in the mean interarrival time of latent sector errors is 0.48×10^2 [3], or equivalently, $ML^{(2)} = 0.48 \times 10^2 \cdot ML^{(1)}$, where $ML^{(1)}$ represents the mean interarrival time of latent errors if there is no intra-disk data redundancy, see Table 1. $ML^{(2)}$ represents the mean interarrival time of latent errors if there is intra-disk data redundancy.

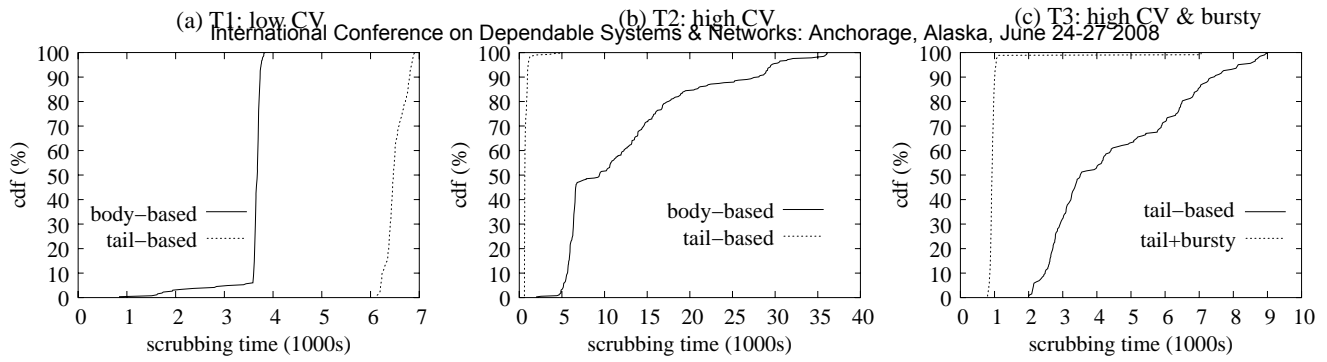


Figure 2. CDF of scrubbing time distribution for traces (a) T1, (b) T2, and (c) T3.

If instantaneous parity (IP) is supported (i.e., parity updates occur without delay), then MTTDL is calculated using Equation (1), where the parameter ML is set as $ML^{(2)}$. If parity updates are delayed, then Equation (1) is modified as follows:

$$MTTDL \approx p \cdot MTTDL_{ML^{(1)}} + (1 - p) \cdot MTTDL_{ML^{(2)}}, \quad (3)$$

where p represents the probability that the parity is dirty, and $MTTDL_{ML^{(1)}}$ and $MTTDL_{ML^{(2)}}$ are computed using Equation (1) with the parameter ML equal to $ML^{(1)}$ and $ML^{(2)}$, respectively. We assume that if the parity is dirty, then latent errors arrive in intervals of $ML^{(1)}$, and that if parity is updated, then errors arrive in intervals of $ML^{(2)}$. We approximate p as the portion of the disk with dirty parity as follows:

$$p \approx \frac{QL_{Update} \cdot Length_{Parity\ segment}}{Capacity_{Disk}} = \frac{RT_{Update} \cdot \lambda_{Update} \cdot Length_{Parity\ segment}}{Capacity_{Disk}}, \quad (4)$$

where QL_{Update} is the average number of dirty parities in the disk, RT_{Update} is the average parity update time, λ_{Update} is the arrival rate of parity updates and $Length_{Parity\ segment}$ is the number of sectors in each parity segment. The performance of the policy to schedule background requests during idle intervals determines RT_{Update} and consequently affects the MTTDL.

In the following, we present results for traces T1 and T2. Traces T2 and T3 yield similar results because both have high variability in idle times and also because for the finite work generated by parity updates exploiting burstiness does not yield any further improvement. The following four metrics are monitored: (a) the MTTDL improvement via intra-disk parity, (b) the ratio of completed parity updates to the total trace WRITE traffic, (c) the average time of parity updates which is the time interval between the completion of

a user-issued WRITE operation and the update of the parity, and (d) the overall (foreground + background) system utilization.

7.2 Parity Updates under Trace T1

Assuming that the disk capacity is 40GB, the relative MTTDL improvement estimated for parity updates under trace T1, which has nearly 40% user WRITES, is given in Table 5. Recall that the relative MTTDL improvement is defined as the difference between MTTDL under the cases with and without intra-disk parity. Here, such an improvement attributed to intra-disk parity is only two orders of magnitude – recall that those attributed to scrubbing are as high as five orders of magnitude. The important result of Table 5 is that there is almost no difference between the MTTDL improvement achieved via instantaneous parity (IP) updates and the delayed parity updates evaluated in this paper, which strongly argues in favor of delayed intra-disk parity. Furthermore, for finite background activities (e.g., parity updates) under trace T1, the tail-based policy achieves slightly better improvement in system reliability than the body-based policy.

Trace	Policy		
	body	tail	IP
T1	0.481×10^2	0.484×10^2	0.484×10^2

Table 5. MTTDL improvement for trace T1 via intra-disk data redundancy, where IP is instantaneous parity update without delaying.

Policy	Completed Ratio (%)	Mean Update Time (s)	System Util (%)
body	38.6	180.6	24.7
tail	41.6	3.3	22.9

Table 6. Parity update performance for trace T1 (low variability).

