Programming Shared-memory Platforms with Pthreads

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Derived from John Mellor-Crummey's COMP422 at Rice University

Topics for Today

- The POSIX thread API (Pthreads)
- Synchronization primitives in Pthreads
  - —mutexes
  - —condition variables
  - —reader/writer locks
- Thread-specific data

POSIX Thread API (Pthreads)

- Standard threads API supported by most vendors
- Concepts behind Pthreads interface are broadly applicable
  - —largely independent of the API
  - —useful for programming with other thread APIs as well
    - Windows threads
    - Java threads
    - …
- Threads are peers, unlike Linux/Unix processes
  - —no parent/child relationship

PThread Creation

Asynchronously invoke `thread_function` in a new thread

```
#include <pthread.h>
int pthread_create(
   pthread_t *thread_handle,  /* returns handle here */
   const pthread_attr_t *attribute,
   void * (*thread_function)(void *),
   void *arg);  /* single argument; perhaps a structure */
```

`attribute` created by `pthread_attr_init`

contains details about

- **whether scheduling policy is inherited or explicit**
- **scheduling policy, scheduling priority**
- **stack size, stack guard region size**

Thread Attributes

Special functions exist for getting/setting each attribute property

e.g., int pthread_attr_setdetachstate(pthread_attr_t *attr, int detachstate)

- **Detach state**
  - PTHREAD_CREATE_DETACHED, PTHREAD_CREATE_JOINABLE
    - reclaim storage at termination (detached) or retain (joinable)
- **Scheduling policy**
  - SCHED_OTHER: standard round robin (priority must be 0)
  - SCHED_FIFO, SCHED_RR: real time policies
    - FIFO: re-enter priority list at head; RR: re-enter priority list at tail
- **Scheduling parameters**
  - only priority
- **Inherit scheduling policy**
  - PTHREAD_INHERIT_SCHED, PTHREAD_EXPLICIT_SCHED
- **Thread scheduling scope**
  - PTHREAD_SCOPE_SYSTEM, ~~PTHREAD_SCOPE_PROCESS~~
- **Stack size**

Wait for Pthread Termination

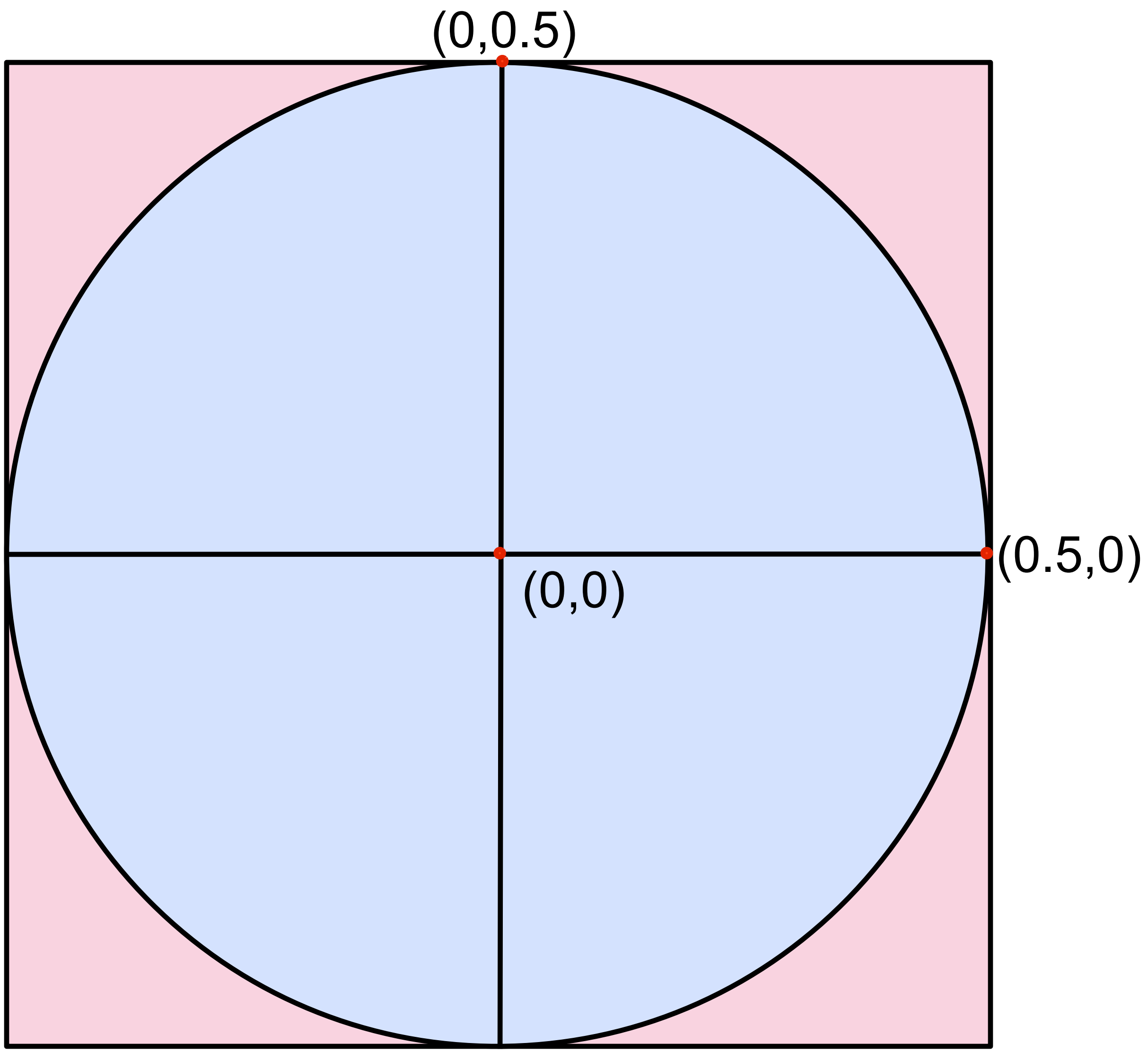
Suspend execution of calling thread until thread terminates

```
#include <pthread.h>
int pthread_join (
  pthread_t thread,  /* thread id */
  void **ptr);  /* ptr to location for return code a terminating
                   thread passes to pthread_exit */
```

Running Example: Monte Carlo Estimation of Pi

Approximate Pi

- —generate random points with x, y $\in$ [-0.5, 0.5]
- —test if point inside the circle, i.e.,
  $x^2 + y^2 < (0.5)^2$
- —ratio of circle to square = $\pi r^2 / 4r^2 = \pi / 4$
- —$\pi \approx 4 *$ (number of points inside the circle) / (number of points total)



Example: Creation and Termination (`main`)

```
#include <pthread.h>
#include <stdlib.h>
#define NUM_THREADS 32
void *compute_pi (void *);
...
int main(...) {
   ...
   pthread_t p_threads[NUM_THREADS];
   pthread_attr_t attr;
   pthread_attr_init(&attr);
   for (i=0; i< NUM_THREADS; i++) {
      hits[i] = 0;
      pthread_create(&p_threads[i], &attr, compute_pi,
         (void*) &hits[i]);
   }
   for (i=0; i< NUM_THREADS; i++) {
      pthread_join(p_threads[i], NULL);
      total_hits += hits[i];
   }
   ...
```

default attributes

thread function

thread argument

Example: Thread Function (`compute_pi`)

```
void *compute_pi (void *s) {
    int seed, i, *hit_pointer;
    double x_coord, y_coord;
    int local_hits;
    hit_pointer = (int *) s;
    seed = *hit_pointer;
    local_hits = 0;
    for (i = 0; i < sample_points_per_thread; i++) {
      x_coord = (double)(rand_r(&seed))/(RAND_MAX) - 0.5;
      y_coord =(double)(rand_r(&seed))/(RAND_MAX) - 0.5;
      if ((x_coord * x_coord + y_coord * y_coord) < 0.25)
          local_hits++;
    }
    *hit_pointer = local_hits;
    pthread_exit(0);
}
```

tally how many random points fall in a unit circle centered at the origin

`rand_r`: reentrant random number generation in [0,RAND_MAX]

Programming and Performance Notes

- Performance on a 4-processor SGI Origin
  - —3.91 fold speedup at 4 threads
  - —parallel efficiency of 0.98
- Code carefully minimizes false-sharing of cache lines
  - —false sharing
    - multiple processors access words in the same cache line
    - at least one processor updates a word in the cache line
    - no word updated by one processor is accessed by another

Example: Thread Function (`compute_pi`)

```
void *compute_pi (void *s) {
    int seed, i, *hit_pointer;
    double x_coord, y_coord;
    int local_hits;
    hit_pointer = (int *) s;
    seed = *hit_pointer;
    local_hits = 0;
    for (i = 0; i < sample_points_per_thread; i++) {
        x_coord = (double)(rand_r(&seed))/(RAND_MAX) - 0.5;
        y_coord =(double)(rand_r(&seed))/(RAND_MAX) - 0.5;
        if ((x_coord * x_coord + y_coord * y_coord) < 0.25)
            local_hits++;
    }
    *hit_pointer = local_hits;
    pthread_exit(0);
}
```

avoid false sharing by using a local accumulator

Data Races in a Pthreads Program

Consider

```
/* threads compete to update global variable best_cost */
if (my_cost < best_cost)
  best_cost = my_cost;
```

—two threads
—initial value of best_cost is 100
—values of my_cost are 50 and 75 for threads t1 and t2

- After execution, best_cost could be 50 or 75
- 75 does not correspond to any serialization of the threads

Critical Sections and Mutual Exclusion

- Critical section = must execute code by only one thread at a time

  /* threads compete to update global variable best_cost */

```
if (my_cost < best_cost)
    best_cost = my_cost;
```

- Mutex locks enforce critical sections in Pthreads
  - —mutex lock states: locked and unlocked
  - —only one thread can lock a mutex lock at any particular time
- Using mutex locks
  - —request lock before executing critical section
  - —enter critical section when lock granted
  - —release lock when leaving critical section

created by `pthread_mutex_attr_init`
specify type:
normal, recursive, errorcheck

- Operations

```
int pthread_mutex_init (pthread_mutex_t *mutex_lock,
    const pthread_mutexattr_t *lock_attr)
int pthread_mutex_lock(pthread_mutex_t *mutex_lock)
int pthread_mutex_unlock(pthread_mutex_t *mutex_lock)
```

atomic operation

Mutex Types

- **Normal**
  - —thread deadlocks if tries to lock a mutex it already has locked
- **Recursive**
  - — single thread may lock a mutex as many times as it wants
    - – increments a count on the number of locks
  - —thread relinquishes lock when mutex count becomes zero
- **Errorcheck**
  - —report error when a thread tries to lock a mutex it already locked
  - —report error if a thread unlocks a mutex locked by another

Example: Reduction Using Mutex Locks

use default (normal) lock type

```
pthread_mutex_t cost_lock;
...
int main() {
   ...
   pthread_mutex_init(&cost_lock, NULL);
   ...
}
void *find_best(void *list_ptr) {
   ...
   pthread_mutex_lock(&cost_lock);   /* lock the mutex */
   if (my_cost < best_cost)
       best_cost = my_cost;
   pthread_mutex_unlock(&cost_lock); /* unlock the mutex */
}
```

critical section

Producer-Consumer Using Mutex Locks

Constraints

- **Producer thread**
  - —must not overwrite the shared buffer until previous task has picked up by a consumer
- **Consumer thread**
  - —must not pick up a task until one is available in the queue
  - —must pick up tasks one at a time

Producer-Consumer Using Mutex Locks

```
pthread_mutex_t task_queue_lock;
int task_available;
...
main() {
    ...
    task_available = 0;
    pthread_mutex_init(&task_queue_lock, NULL);
    ...
}
void *producer(void *producer_thread_data) {
    ...
    while (!done()) {
       inserted = 0;
       create_task(&my_task);
       while (inserted == 0) {
           pthread_mutex_lock(&task_queue_lock);
           if (task_available == 0) {
              insert_into_queue(my_task); task_available = 1;
              inserted = 1;
           }
           pthread_mutex_unlock(&task_queue_lock);
       }
    }
}
```

critical section

Producer-Consumer Using Locks

```
void *consumer(void *consumer_thread_data) {
    int extracted;
    struct task my_task;
    /* local data structure declarations */
    while (!done()) {
       extracted = 0;
       while (extracted == 0) {
          pthread_mutex_lock(&task_queue_lock);
          if (task_available == 1) {
             extract_from_queue(&my_task);
             task_available = 0;
             extracted = 1;
          }
          pthread_mutex_unlock(&task_queue_lock);
       }
       process_task(my_task);
    }
```

critical section

Overheads of Locking

- Locks enforce serialization
  - —threads must execute critical sections one at a time
- Large critical sections can seriously degrade performance
- Reduce overhead by overlapping computation with waiting

```
int pthread_mutex_trylock(pthread_mutex_t *mutex_lock)
```

  - —acquire lock if available
  - —return EBUSY if not available
  - —enables a thread to do something else if lock unavailable

Condition Variables for Synchronization

Condition variable: associated with a predicate and a mutex

- **Using a condition variable**
  - **—thread can block itself until a condition becomes true**
    - **thread locks a mutex**
    - **tests a predicate defined on a shared variable**
      - **if predicate is false, then wait on the condition variable**
        - **waiting on condition variable unlocks associated mutex**
  - **—when some thread makes a predicate true**
    - **that thread can signal the condition variable to either**
      - **wake one waiting thread**
      - **wake all waiting threads**
    - **when thread releases the mutex, it is passed to first waiter**

Pthread Condition Variable API

```
/* initialize or destroy a condition variable */
int pthread_cond_init(pthread_cond_t *cond,
    const pthread_condattr_t *attr);
int pthread_cond_destroy(pthread_cond_t *cond);

/* block until a condition is true */
int pthread_cond_wait(pthread_cond_t *cond,
    pthread_mutex_t *mutex);
int pthread_cond_timedwait(pthread_cond_t *cond,
    pthread_mutex_t *mutex,
    const struct timespec *wtime);

/* signal one or all waiting threads that condition is true */
int pthread_cond_signal(pthread_cond_t *cond);
int pthread_cond_broadcast(pthread_cond_t *cond);
```

abort wait if time exceeded

wake one

wake all

Condition Variable Producer-Consumer (`main`)

```
pthread_cond_t cond_queue_empty, cond_queue_full;
pthread_mutex_t task_queue_cond_lock;
int task_available;
/* other data structures here */
main() {
    /* declarations and initializations */
    task_available = 0;
    pthread_init();
    pthread_cond_init(&cond_queue_empty, NULL);
    pthread_cond_init(&cond_queue_full, NULL);
    pthread_mutex_init(&task_queue_cond_lock, NULL);
    /* create and join producer and consumer threads */
}
```

default initializations

Producer Using Condition Variables

```
void *producer(void *producer_thread_data) {
    int inserted;
    while (!done()) {
        create_task();
        pthread_mutex_lock(&task_queue_cond_lock);
        while (task_available == 1)
            pthread_cond_wait(&cond_queue_empty,
                &task_queue_cond_lock);
        insert_into_queue();
        task_available = 1;
        pthread_cond_signal(&cond_queue_full);
        pthread_mutex_unlock(&task_queue_cond_lock);
    }
}
```

note loop

releases mutex on wait

reacquires mutex when woken

Consumer Using Condition Variables

```
void *consumer(void *consumer_thread_data) {
    while (!done()) {
        pthread_mutex_lock(&task_queue_cond_lock);
        while (task_available == 0)
            pthread_cond_wait(&cond_queue_full,
                &task_queue_cond_lock);
        my_task = extract_from_queue();
        task_available = 0;
        pthread_cond_signal(&cond_queue_empty);
        pthread_mutex_unlock(&task_queue_cond_lock);
        process_task(my_task);
    }
}
```

note loop

releases mutex on wait

reacquires mutex when woken

Composite Synchronization Constructs

- Pthreads provides only basic synchronization constructs
- Build higher-level constructs from basic ones
  - e.g., work queues, dynamic load balancing ...

Reader-Writer Locks

- **Purpose: access to data structure when**
  - —frequent reads
  - —infrequent writes
- **Acquire read lock**
  - —OK to grant when other threads already have acquired read locks
  - —if write lock on the data or queued write locks
    - – reader thread performs a condition wait
- **Acquire write lock**
  - —if multiple threads request a write lock
    - – must perform a condition wait

Read-Write Lock Sketch

- Rather than using pthread_rwlock, you could build your own using basic primitives
- Use a data type with the following components
  - a count of the number of active readers
  - 0/1 integer specifying whether a writer is active
  - a condition variable `readers_proceed`
    - signaled when readers can proceed
  - a condition variable `writer_proceed`
    - signaled when one of the writers can proceed
  - a count `pending_writers` of pending writers
  - a mutex `read_write_lock`
    - controls access to the reader/writer data structure

Thread-Specific Data

Goal: associate some state with a thread

- **Choices**
  - —pass data as argument to each call thread makes
    - – not always an option, e.g. when using predefined libraries
  - —store data in a shared variable indexed by thread id
  - —<u>using thread-specific keys</u>
- **Why thread-specific keys?**
  - —libraries want to maintain internal state
  - —don't want to require clients to know about it and pass it back
  - —substitute for static data in a threaded environment
- **Operations**

associate NULL with key in each active thread

```
int pthread_key_create(pthread_key_t *key, void (*destroy)(void *))
int pthread_setspecific(pthread_key_t key, const void *value)
void *pthread_getspecific(pthread_key_t key)
```

retrieve value for current thread from key

associate (key,value) with current thread

Thread-Specific Data Example: Key Creation

Example: remember performance information for a thread

```
#include <pthread.h>
static pthread_key_t profiler_state;
initialize_profiler_state() {
   …
   pthread_key_create(&profiler_state,
                      (void *) free_profile);
   …
}
void free_profile(profile *my_profile) {
  free(my_profile);
}
```

opaque handle used to locate thread-specific data

destructor for key value

Thread-Specific Data Example: Specific Data

Example: remember profiler state for a thread

```
void init_thread_profile(…) {
   profile *my_profile = (profile *) malloc(…);
   pthread_setspecific(profiler_state, (void *) my_profile);
   …
}
void update_thread_profile(...) {
  profile *my_profile = (profile *)
                          pthread_getspecific(profiler_state);
  // update profile
}
```

References

- Adapted from slides “Programming Shared Address Space Platforms” by Ananth Grama.
- Bradford Nichols, Dick Buttlar, Jacqueline Proulx Farrell. “Pthreads Programming: A POSIX Standard for Better Multiprocessing.” O'Reilly Media, 1996.
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